1 **Revised Consolidated Response to Reviewers**

We sincerely thank all reviewers for their insightful comments, which have greatly improved the manuscript. This document provides point-by-point responses, detailing the revisions made to address each comment while maintaining the original intent

5 **Response to Reviewer #1**

6 **Reviewer's Comment 1:**

I would recommend increasing the size of Figure 1. At its present size, it is difficult to
read without zooming in very closely.

9 **Response:**

10 Thank you for the suggestion regarding Figure 1's readability. We have increased both11 the size and resolution of Figure 1. Specifically, we have:

12 Enlarged the figure

- 13 Increased the resolution
- 14 Enhanced the contrast of the curve lines and axis labels

15 **Changes in Manuscript:**

16 We have increased the size and resolution of Figure 1 to improve its readability and 17 ensure all details are clearly visible.

18 **Reviewer's Comment 2:**

In line 88, is the parameter a just a numerical parameter, or does it have a name ordefinition?

21 **Response:**

Thank you for pointing out the need to clarify parameter a. In the revised manuscript, we have added a clear definition of this parameter. As shown in lines 84-85 of the revised manuscript, we now explicitly state that "a is a dimensionless control parameter that governs the system's nonlinear characteristics." This parameter was originally introduced by Agop et al. (2012) (referenced in line 83) to describe the system's nonlinear behavior.

27 Changes in Manuscript:

In line 84, we have added the following definition: "where a is a dimensionless control parameter that governs the system's nonlinear characteristics".

30 **Reviewer's Comment 3:**

In lines 91–93, the change in potential profile against current is discussed in Figure 1. Within these lines, there is mentioned a "certain state" and a "certain limit," as well as a "completely different state" before reaching steady state. Be more specific with what these thresholds and states really are, and if possible postulate on how they might come to be.

35 **Response:**

36 Thank you for requesting clarification about the state transitions. We have revised lines

37 91-98 in the manuscript to provide precise definitions and explanations of these states:

38 "Certain state": Now defined in line 91 as the initial stable state (Point A in Figure 1),
39 characterized by monotonic current increase with voltage.

40 "Certain limit": Explained in lines 92-93 as critical threshold points (Points B and D)
41 that mark transitions between stable states.

42 "Completely different state": Defined in lines 94-95 as the high-conductivity stable
43 state (Point C) after transition.

44 Changes in Manuscript:

45 We have revised lines 91-98 as follows:

46 "As illustrated in Figure 1, for parameter a, the J- ϕ characteristic curve exhibits three 47 distinct regions. There are two stable regions where dJ/d ϕ > 0: a low-conductivity state 48 (segment AB) and a high-conductivity state (segment CD), both characterized by a 49 monotonically increasing current with voltage. These stable regions are separated by an 50 unstable region where dJ/d ϕ < 0, demonstrating negative differential resistance"

51 **Response to Reviewer #2**

52 **Reviewer's Comment 1:**

The main concern regards the connection between the formalism introduced in Section 2.2 and the formalisms and results presented in Sections 2.4 and 3. Indeed, what has been introduced in Section 2.2 is a classical theory of bifurcation for autonomous dynamical systems being written as a time-evolution mapping (continuous in this case) with a not 57 implicit dependence on time in the forcing term. Conversely, what is introduced Eq. (10) 58 is a non-autonomous dynamical system whose implicit variable is not time but one of the 59 state variables (I). Thus, the connection among fixed points, instability, and other types of 60 concepts cannot be simply ruled out. What the authors introduced in Eq. (10) is a 61 mathematical description of the manifold or a dynamical bifurcation scenario for, at least, 62 a 2-D dynamical system described by the state variables U and I. The authors need to 63 carefully address these concepts and revise accordingly the manuscript by possibly considering a 2-D dynamical system of the form 64

65 $dU/dt = f(U, I, u_parameters)$

66 $dI/dt = g(I, U, i_parameters)$

67 where u_parameters and i_parameters refer to the bifurcation parameters leading 68 eventually to critical transitions in the system.

69 **Response:**

Thank you for your insightful comment regarding the mathematical framework. We need to clarify that Equation (10), appearing in lines 160-165 of the revised manuscript, represents a calculation of differential resistance (dU/dI) rather than a dynamical system. The theoretical framework introduced in Section 2.2 establishes the connection between negative differential resistance and system instability, which we then apply to analyze lightning channel behavior.

Thank you for your valuable suggestion regarding the mathematical framework. Weneed to clarify several key points:

78 **Framework Clarification (lines 160-165):**

Equation (10) represents a calculation method rather than a dynamical system

80 The equation describes instantaneous channel properties rather than temporal evolution

81 **Connection Between Sections:**

- 82 Section 2.2 (lines 103-110): Establishes theoretical foundation for stability analysis
- 83 Section 2.4 (lines 160-165): Derives differential resistance calculation
- 84 Section 3 (lines 170-190): Applies framework to physical system

85 Relationship to Suggested 2-D System:

- 86 While we appreciate the suggestion of a 2-D system, our focus is on the instantaneous
- 87 relationship between voltage and current rather than temporal dynamics.
- 88 Changes in Manuscript:

89 We have made the following revisions in Section 2.4 (lines 160-165):

90 "The differential resistance of a streamer channel is determined by the potential 91 difference U across the streamer zone of the leader head and the channel current I. Equation 92 (10) provides a mathematical expression for calculating this differential resistance, which 93 serves as an indicator of channel stability rather than describing temporal evolution of the 94 system"

95 **Reviewer's Comment 2:**

96 The second main concern is related to Figure 2. Indeed, what the authors reported is 97 valid for bi-stable dynamical systems which are described by a double-well potential 98 function. It is not straightforward the connection with Eq. (1) and the system introduced in 99 Line 103 which seems to be more similar to a hysteresis cycle. Which are the stable and 100 unstable fixed points in your system? If φ is treated as a parameter the system admits 3 101 fixed points provided that $J \neq 0$ and J is real. However, limit cycles could emerge when 102 crossing the complex plane (Hopf bifurcation). Thus, more careful analysis of the 103 bifurcations should be carried out.

104 **Response:**

105 Thank you for raising these important points about the system's behavior and Figure 2.

106 We have substantially revised our explanation in the manuscript to clarify:

107 The relationship between Equation (1) and system stability (lines 103-110):

- 108 For small a: monostable behavior with monotonic current-voltage relationship
- 109 For larger a: bistable behavior with negative differential resistance region

110 The physical interpretation of Figure 2 (following line 110):

- 111 Valleys represent stable states (low and high conductivity states)
- 112 Peaks correspond to unstable transition points
- 113 Points F1 and F2 mark critical transitions between states

114 **Connection to Physical System:**

- 115 Low-conductivity state: Initial channel condition
- 116 High-conductivity state: Fully developed discharge
- 117 Transitions: Observed as sudden channel brightening or extinction"

118 **Changes in Manuscript:**

119 We have enhanced the explanation in lines 103-110 to read:

120 "In nonlinear dynamics, negative differential resistance, bistability, and hysteresis are

121 commonly observed. Considering the dynamic system $dJ/dt = f(J,\phi)$, where J is the state

- 122 variable and φ is a parameter. The equilibrium points are given by $f(J,\varphi) = 0$. At an
- 123 equilibrium point, the system is unstable when $\partial f/\partial J > 0$ and stable when $\partial f/\partial J < 0$."

124 **Reviewer's Comment 3:**

125 The third main concern is related to the presentation of the results and the overall 126 structure of the manuscript. The authors need to carefully revise the manuscript to improve 127 the quality of the figure as well as to check the consistency of the different type settings of 128 the text, typos, references, etc.

- 129 Please find a list below.
- 130 Check the font size for subsections
- 131 Check the font type for references through the text (sometimes italics, sometimes not)
- 132 All figures need to be improved for quality
- 133 Line 84: mismatching between φ and that used in Eq. (1)
- 134 Figure 1: increase font and labels
- 135 Line 104: missing definition of φ

Line 105: formally, the condition for fixed points should be met not for all J but for aspecific solution J* or something similar

- Line 106: missing definition of what the subscript J means (I assume derivative withrespect to J)
- 140 Line 106: missing space and capital letter "if we let"
- 141 Line 110: the assumption is not straightforward and the connection between Eq. (1) and
- 142 Line 103 is missing
- 143 Line 139: please delete double point.
- 144 Line 140: please delete the period before introducing the equation.
- 145 Line 145: which type of fit is used?
- 146 Figure 3: missing space Fig3
- 147 Figure 4: missing space Fig4
- 148 Figure 5: missing space Fig5.

149 **Response:**

150 Thank you for your thorough review of the technical details. We have made 151 comprehensive revisions throughout the manuscript to address all formatting and 152 consistency issues:

153 **Changes in Manuscript:**

154 1. Typography and Formatting:

- 155 Standardized subsection font sizes throughout
- 156 Unified reference formatting to non-italic style
- 157 Corrected figure spacing (e.g., "Fig. 3" instead of "Fig3")

158 **2. Mathematical Notation:**

- 159 Lines 84-85: Added consistent φ notation
- 160 Line 104: Added explicit definition of φ
- 161 Line 105: Clarified fixed point conditions
- 162 Line 106: Added definition of subscript J

163 **3. Figure Quality:**

- 164 Enhanced resolution of all figures
- 165 Increased font sizes in labels and annotations
- 166 Standardized figure formatting

167 **4. Technical Content:**

- 168 Line 145: Added explanation of fitting method: "Used nonlinear least squares fitting
- 169 with double power-law model $E = aI^b + cI^{d''}$
- 170 Improved equation presentation and formatting throughout
- 171 Response to Reviewer #3

172 **Reviewer's Comment**

The manuscript explores stability and critical transitions in lightning discharge channels using concepts from nonlinear dynamics, particularly bi-stable systems. I recommend acceptance contingent upon revision. While Figures 1 and 2 effectively demonstrate the theoretical principles, they remain too abstract and do not correspond directly with the specific dynamics of lightning channels discussed. I suggest adding figures that depict the stability profiles derived from equations 9 and 10, as these directly describe the behavior of lightning systems. This enhancement will clarify the instability mechanisms within real 180 lightning channels, making the application of theoretical models more comprehensible and

181 scientifically rigorous.

182 **Response:**

183 Thank you for your constructive suggestion regarding the theoretical and practical 184 aspects of our analysis. We need to clarify that Equations (9) and (10) represent 185 calculations of potential difference and differential resistance rather than dynamical system 186 equations. These equations directly relate to the physical behavior of lightning channels as 187 follows:

188 Equation (9) (lines 170-175) calculates the total potential difference across the leader-189 streamer system.

Equation (10) (lines 175-180) determines the differential resistance, which indicatessystem stability.

192 Changes in Manuscript:

193 We have enhanced the explanation in Section 3 (lines 170-190) to clarify how these 194 equations relate to physical observations: Section 3 (lines 170-190) now reads: "The 195 theoretical framework established by Equations (9) and (10) directly corresponds to 196 measurable lightning channel characteristics. Figure 4 demonstrates this connection by 197 showing how differential resistance varies with channel current, identifying critical transition points that match observed behavior. The intersection points with zero 198 199 differential resistance correspond to stability thresholds observed in lightning 200 measurements."

201 Summary of Major Changes

- 202 We have made the following substantial improvements to the manuscript:
- 203 1. Enhanced theoretical framework clarity and connections
- 204 2. Improved mathematical consistency and notation
- 205 3. Upgraded figure quality and presentation
- 206 4. Strengthened links between theory and physical application
- 207 5. Standardized formatting throughout

We believe these revisions have substantially improved the manuscript while maintaining its scientific contribution. We again thank all reviewers for their valuable input.