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Dear Dr. Juan Restrepo,

My co-authors and I are very thankful for the reviewers' comments which resulted in an improved and substantially revised manuscript. In our original version of the manuscript we had investigated the possibility of simulating regime dynamics in the stably stratified nocturnal boundary layer (SBL) with a stochastic parameterisation on the basis of stationary Markov chains. Such an approach is independent of the state of the atmospheric boundary layer. Due to the fact that such a model had not satisfactorily approximate SBL regime dynamics we had envisioned a possible SBL state-dependent explicitly stochastic parameterisation in the discussion. As suggested by reviewer number 1, however, in the revised manuscript we actually have developed this envisioned explicitly stochastic parameterisation. Therefore, we have included a new section to the manuscript in which we do not only develop the parameterisation but also test it in an idealised single column model. The suggested alterations and enhanced analyses have resulted in a substantially restructured and revised manuscript with the following changes:

1. We would like to change the title from "Characterising regime behaviour in the stably stratified nocturnal boundary layer on the basis of stationary Markov chains" into "A prototype stochastic parameterisation of regime behaviour in the stably stratified atmospheric boundary layer" which is now more appropriate.
2. Amber M. Holdsworth is introduced as a third author.
3. The section about the investigation how well stationary Markov chains can simulate SBL regime dynamics (section 4) has been substantially shortened and summarised to the main key points:
 - a. Stationary Markov chains using transition probabilities as estimated from observations are unable to approximate SBL regime dynamics accurately as nonstationarities and non-Markov behaviour are too prevailing.
 - b. SBL regime dynamics as estimated from observations are relatively insensitive to the actual transition probability matrix allowing for an investigation of a larger range of different transition probabilities in a stationary Markov chain.
 - c. Stationary Markov chains are also unable to approximate SBL regime dynamics of interest even if a relatively broad range of transition probabilities and seasonal nonstationarities are accounted for.

- d. The presented results demonstrate that state-dependent parameterisations for the SBL regime dynamics are necessary.
4. A fifth section is added evaluating state-dependent transition probabilities conditioned on different stability variables of the SBL. This information is used in order to develop a state-dependent explicitly stochastic parameterisation for SBL regime dynamics which is then tested in an idealised single column model.
5. The discussion and conclusion section is substantially shortened as the stochastic parameterisation is actually developed and tested. Instead, the potential of such stochastic parameterisation is evaluated.

We think that the revised manuscript is a much improved contribution to the SBL community as it does not only show that stationary Markov chains are inappropriate to simulate SBL regime dynamics but also offers a potential possibility to account for SBL regime dynamics through state-dependent explicitly stochastic parameterisations in models for weather and climate in the near future.

We have adopted the following modifications to the manuscript and replies to the reviewers (**bold**) are provided in *italic* characters. Within the revised manuscript (with tracked changes) modified text is indicated in red.

Thank you very much for considering our manuscript for publication.

Sincerely,

Carsten Abraham

Anonymous Referee #1

Summary: Stationary Hidden Markov models (HMM) are fitted based on long timeseries obtained from meteorological tower, using Reynolds averaged meteorological state variables (wind speed, wind shear and stratification). The HMM classifies the data into two regimes, corresponding to weakly stable boundary layers (wSBL) and very stable boundary layers (vSBL). The fitted stationary models are used to obtain statistics of regime occurrences, regime transitions or time between transitions. The HMM estimation provides a transition probability matrix describing regime transitions, and the sensitivity of regime statistics to the matrix values is studied. The authors discuss limitations of the stationarity assumption in the model and acknowledge a need to account for external influences in the transition probability matrix. The dynamics of transitions are shown not to fit the Markovianity assumption. An idea to use a state dependent Markov model, or regime transition probability matrix, in a turbulent kinetic energy budget closure in a weather or climate model is sketched as a conclusion.

General comments: The idea of including a stochastic representation of SBL regime transitions in a turbulence parameterization for weather or climate models is interesting, and suggesting ways to do so is a welcome contribution. As discussed by the authors in the introduction, models have been proposed to explain transitions from weakly stable to very stable states, but no model exist to represent a recoupling of turbulence to the surface after a decoupled state, or in other words to represent transitions from vSBL to wSBL. Numerous observational studies show events such as gravity waves, instabilities or other types of non-turbulent motions connected to a transition from vSBL to wSBL and such transitions take a rather random character. Therefore, proposing to represent such transitions as a stochastic process is an interesting direction. Yet, the presented study falls short in several aspects. The authors start by discussing HMM analyses of the considered tower data which are presented in parallel papers and which give clear signs of non-stationarity and non-Markovianity in the regime statistics. Nevertheless, the authors choose to present the statistics of regime transitions and occurrences that result from a stationary Markov model and to compare those to the observational statistics, justifying this choice by the wish to test the simplest possible approach. The comparison not surprisingly shows the need to include non-stationarity in the model of regime transitions, as was already discussed by the authors based on the HMM analyses in the cited submitted papers. I am not convinced that this is a very important additional contribution. Discussion of ways to consider non-stationarity in the model is kept to a minimum. Further, the non-stationarity is attributed to external influences, such as synoptic meteorological states (cloud cover, geostrophic wind for example, as was also described in Monahan et al. 2015, JAS). This is a very relevant and important fact, and the work should at the very least discuss methods that provide means of estimating non-stationary models of regime transitions explicitly influenced by external factors, and at best include non-stationarity in the model. Methods to include

explicit influence by external factors have been proposed and implemented in atmospheric applications, including to describe SBL regime transitions (eg: Horenko 2010; Metzner et al., 2012; O’Kane et al 2013; Vercauteren and Klein 2015).

>>>We are very thankful for the general evaluation of the reviewer and understand very well that our first manuscript came short in many aspects. The manuscript has been substantially revised and restructured to address the reviewer’s concerns. As remarked by the reviewer a state-independent HMM-based Markov-chain parameterization (which is investigated to evaluate if such a simple approach suffice to simulate SBL dynamics) is not able to simulate SBL regime dynamics which is why we have substantially shortened and summarised this discussion. Instead, we have extended the discussion by presenting an explicitly stochastic, state-dependent parameterisation of regime dynamics which is able to account for the SBL regime dynamic features of interest.

The need for state dependent transition probabilities, in a stochastic model that would be implemented in the turbulence closure scheme of atmospheric models, is emphasized rightfully and the authors suggest to relate it to the Richardson number. Why not test a Ri number dependence on the transition probability in this paper? That would make the analysis much stronger. The HMM framework is suggested as a foundation for a new parameterization of SBL turbulence, and discussion on how the authors would see such a turbulence parameterization could be expanded. The suggestion is to include random “kicks” of TKE in the vSBL regime, which in turn affect Ri and eventually a transition to wSBL could occur such as no extra TKE source term will be added anymore. Can the authors give ideas on how such a noise term could be defined? And how could such a parameterization fit with the conclusion of the present study, which state: 1- that a stationary Markov chain is inappropriate to represent wSBL to vSBL transition such as driven by radiative cooling. 2- it is inappropriate to represent the statistics of persistent wSBL and vSBL nights as those are impacted by external influences or large-scale synoptic forcing which induces nonstationary behaviour. 3- it could be appropriate to represent a vSBL to wSBL transition after an initial wSBL to vSBL transition. The third point fits with observational and DNS evidence of perturbations that can drive the vSBL back to a wSBL (such as the DNS of Donda et al. 2015, which are cited but not in this context). The authors could also discuss efforts that have been made to describe such “random” perturbations (eg Kang et al. 2014; 2015), which could help giving a stochastic description of the random perturbations, if not of the impact on the TKE itself.

>>>We are very thankful for the suggestion of the reviewer to actually write down a state-dependent stochastic parameterisation which is now done in section 5. First we investigate the state-dependent transition probabilities conditioned on internal state variables (cf. section 5.1). In section 5.2 we then develop the complete stochastic parameterisation for first order TKE closure models. During building a prototype stochastic parameterisation, we have decided that if we actually develop the stochastic parameterization, preliminary tests in an idealised single column model would better demonstrate its feasibility. That is the reason why we included some results showing that the conceptual framework shows potential of reasonably well representing the SBL regime dynamics for weather and climate models (cf. section 5.3). Due to the length of the paper (with the new section 5) we refrain from

discussing detailed sensitivity analyses of this parameterisation which will be done in a future study.

Specific comments:

1- P1 L20: I would suggest to replace “collapsed turbulence” by intermittent turbulence, or turbulence which does obey Monin Obukhov Similarity Theory. Discussion paper about modeling difficulties for the turbulence would be appropriate to justify the need for stochastic parameterisation.

>>>We have replaced the description of the turbulence in the two different regimes as suggested (cf. p. 1 ll. 18-24). Furthermore, in the revised manuscript we discuss in more detail why current SBL parameterisations of the SBL fail to reproduce the regime dynamics (cf. p. 1 ll. 24-25 to p. 2 ll. 1-7). The need for stochastic parameterisations is described on p. 3 ll. 15-31.

2- P2 L30: unrealistic decoupling is also connected to misrepresentation of the TKE. This point could be discussed.

>>>The fact that the unrealistic decoupling is related to the misrepresentation of the TKE has been added. (cf. p. 3 l. 4)

3- P3 L20: The point of representing regime transitions as a stochastic process is clear, but what kind of parameterization is envisioned in each regime?

>>>A better characterisation of stochastic parameterisation, its general idea, and why SBL dynamics might profit from it has been described (cf. p. 4 ll. 3-5).

L25: seasonal dependence: is it not more accurately a dependence on external influences? Such influences have been included in non-stationary regime classification schemes (see general comments).

>>>As described in the general comments we wanted to first investigate if state-independent parameterisations suffice to simulate SBL regimes. Due to the weakness and inability of stationary Markov chains to account for all SBL regime dynamics of interests, a more complex state-dependent stochastic parameterisation is envisioned. The state-dependent explicitly stochastic parameterisation presented in section 5 should be able to capture such non-stationary behaviour.

4-5 P4 L30: the assumptions deserve discussion. The Markovianity assumption could be tested or relaxed, see eg. Franzke et al. 2009. The stationarity assumption is not fulfilled. P5 L15: work on non-stationary statistical clustering should be discussed (see general comments and references).

>>>Work on nonstationary approaches to cluster the data are briefly discussed and why we consider the stationary approach in the first place has been justified more clearly (cf. p. 6 ll.11-23).

6- P6 L5: the fact that the influence of seasonal changes is due to changes in the meteorological state means that explicit external influences would improve the model dramatically. Please discuss how to take those into account.

>>>As described above the state-dependent explicitly stochastic parameterisation should be able to account for the seasonal dependencies through state-dependent transition probabilities.

7- Section 4.1: shouldn't the comparison of observation and stationary Markov chain calculation be done for separate time periods? It could be more appropriate to compare the model results with the observational statistics by dividing the dataset in a training part and a control part.

>>>We are thankful for the reviewer's reminder to be careful to consider potential overfitting by assessing our model performance against the same data used to estimate model parameters. Our results show that the 'freely-running' stationary Markov chain does generally not suffice to describe SBL regime dynamics as estimated from observations which is why we argue that state-dependent stochastic parameterisations are needed. Therefore, we think that a potential overfitting by using the same data to estimate transition probabilities and regime statistics against which we assess the model performance is not a primary concern.

8- L 15-25: Can the results be discussed in light of, eg., the theoretical work of wSBL to vSBL transitions (the MSHF framework by van de Wiel et al. discussed in the introduction). The importance of physical factors highlighted in this model is not included in the Markov model, again potentially calling for inclusion of external factors.

>>>The new explicitly stochastic parameterisation is generally able to account for these processes if only in a simplified manner.

9- L30: here the fact that the stationarity assumption gives satisfactory results is probably consistent with the physical ideas of transitions being linked to random intermittent events. This could be discussed in the context of existing work (see general comments).

>>>Due to the fact that we have extended the discussion of the new proposed stochastic parameterisation we have shortened the whole Markov chain discussion to a minimum and refrain from discussing how some aspects might or might not be well simulated by Markov chain approximations.

10- P7 L5-10 and Fig 5: Do the pdfs show the probability of time spent in a state? The text and the figure caption do not seem to match, or rather, the figure caption is not informative as it is.

>>>Yes, the distributions show the time spent in one state or the event duration. Due to the restructuring we have changed the Figure substantially including its caption to make it more informative (cf. Figure 4).

Moreover I do not really understand the grey band. Why is the width of the distribution so dependent on time after sunset? How is the width of the band calculated? How about the seasonal dependence of the time between transitions? Since it was shown to be critical, why forget it here?

>>>We acknowledge that our description of that analysis was unclear as we compared non seasonal (observations) with seasonal dependencies (FSMC). The event duration pdfs do not change substantially across the seasons except from the fact that the occurrence of longer event durations become more likely as nights simply have more time for such events to occur. Therefore, we analyse all data and compare those to FSMC event duration probabilities computed for nights lasting 12 hours as an intermediate value representative for all seasons. Detailed analyses of the seasons do not add any substantial content to the discussion. We have changed the Figure 4 and have adopted a more consistent description of the results (cf. p. 7 l. 28 to p.8 l.3).

Relaxation time: I believe that this could be considered by including finite memory in the Markov model (cf Franzke et al. 2009). The inclusion of explicit external influences should be discussed.

>>>The recovery period is now accounted for in our explicitly stochastic parameterisation.

11- P8 L20-30 and Fig 7: each colour has a different number of dots, and the caption does not state what individual dots represent. The discussion actually presents results of an analysis which is different than the one presented in this paper and is already presented in the submitted paper cited as a reference. I do not believe that the results and conclusions should be repeated here. The authors could simply state the conclusions of this parallel study in the discussion.

>>>As suggested we have removed this Figure and the discussion from paper.

12- P9 L5: Table 3 only shows the observed probabilities and not a comparison of theoretical and observed.

>>>That is correct. We have changed the formulation that it is clearer that Table 3 shows only the occupation statistics as estimated from observations and we compare those to calculations in the freely-running Markov chain as presented in the Figures. (cf. p. 9 ll. 9-11).

13- Figure 10: what are the grey dots in the figure?

>>>The grey dots are regions where the total VP consistency frequently changes. This Figure, however, has been removed from the discussion as it did not add any important information for the discussion and the results have been briefly summarised (cf. p. 9 ll. 28-33).

14- P10 L30: Figure 12 does not exist.

>>> The enumeration of the figures in the submitted manuscript is such that "Figure 12" denotes the second figure.

15- P11 L5: how are non-stationarities considered in the analysis? If the stationary Markov chain is defined differently for each season, this is not stated very clearly.

>>>Due to the restructuring this part has been eliminated from the discussion.

16- P11 L30: "The event duration probability density functions . . . display a maximum an hour or two after sunset" I am confused here. I had understood that the figure showed the pdfs of event duration, or time between two transitions. That has nothing

to do with the sunset time (And the sunset time is not mentioned in the figure caption either), but would fit with the recovery time idea which is discussed by the authors.

>>>We are very thankful to the reviewer for catching this mistake. This was completely wrong and the sentences have been eliminated.

Anonymous Referee #2

This is a well-written paper on the characterization of the nocturnal boundary layer in terms of Markov chains. The authors utilize measured data and define a hidden Markov model (HMM). Next they estimate the HMM parameters using a maximum likelihood approach. The work is interesting and the model seems to be well thought. The authors present a convincing comparison of the trained model with observations and they also perform a rigorous sensitivity analysis. The only point that I believe should the authors spend more effort is a more detailed discussion on the justification of the Markov assumption in terms of the physical properties of the nocturnal boundary layer. This should be particularly useful especially for non-experts on SLB.

>>>We are very thankful for the reviewer's suggestion to justify the assumptions of the Markov model approach in terms of its applicability for stable boundary layer regime dynamics in more detail. In the introduction of the new manuscript we justify our choice of testing the Markov model assumption as a foundation for SBL regime dynamics (cf. p.4 ll. 1-11). However, as it turns out the Markov model does not suffice to model SBL regime dynamics (p.10 ll. 1-5) we do not overrate its potential and do not try to speculate which particular physical properties might or might not be approximated by a Markov assumption. Instead, we lead the discussion to the finding that additional complexity in a possible stochastic parameterisation is needed (state dependent transition probabilities; section 5.1) and how we can develop a realistic yet simple stochastic parameterisation (cf. section 5.2). Justification for particular choices of building the stochastic parameterisation representing typical physical SBL phenomena are stated in those sections.

Anonymous Referee #3

>>>We are very thankful to the reviewer for the suggestion to improve our manuscript, in particular for the detailed correction of our equations describing the hidden Markov model. We did not submit the current study as a Part IV extension to our J.Atmos.Sci. series as that paper series deals with determining the climatology of SBL regime dynamics across the tower data which is also used for this study. In contrast to those climatologies, the paper at hand is intended to work towards stochastic parameterisations of turbulence in the SBL which we found more appropriate as a stand alone paper in this Journal. As we have included the discussion of a parameterisation and its test in a single column model (as suggested by reviewer#1) which has lead to a complete new paper structure, the paper is related to the previous studies to a lesser extent.

Comments 1-3: As mentioned above we are very thankful for the careful and detailed corrections of our equations describing the assumptions for the HMM analysis. We have

adopted your suggestions to correct our equations and hope that they have also become easy to understand (cf. section 3 of the new manuscript).

Comment 4: The term “diel” has been changed to “diurnal”

A prototype stochastic parameterisation of regime behaviour in the stably stratified atmospheric boundary layer

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Abstract. Recent research has demonstrated that hidden Markov model (HMM) analysis is an effective tool to classify atmospheric observations of the stably stratified nocturnal boundary layer (SBL) into weakly stable (wSBL) and very stable (vSBL) regimes. Here we consider the development of explicitly stochastic representations of SBL regime dynamics. First, we analyse if HMM-based SBL regime statistics (the occurrence of regime transitions, subsequent transitions after the first, and very persistent nights) can be accurately represented by ‘freely-running’ stationary Markov chains (FSMC). Our results show that despite the HMM-estimated regime statistics being relatively insensitive to the HMM transition probabilities, these statistics cannot all simultaneously be captured by a FSMC. Furthermore, by construction a FSMC cannot capture the observed non-Markov regime duration distributions. Using the HMM classification of data into wSBL and vSBL regimes, state-dependent transition probabilities conditioned on the bulk Richardson number (Ri_B) or the stratification are investigated. We find that conditioning on stratification produces more robust results than conditioning on Ri_B . A prototype explicitly stochastic parameterisation is developed based on stratification-dependent transition probabilities, in which turbulence pulses (representing intermittent turbulent events) are added during vSBL conditions. Experiments using an idealised single column model demonstrate that such an approach can simulate realistic-looking SBL regime dynamics.

1 Introduction

A common classification scheme of the stably stratified atmospheric boundary layer (SBL) distinguishes between two distinct regimes, denoted the weakly and very stable boundary layers (respectively wSBL and vSBL, e.g. Mahrt, 1998a; Acevedo and Fitzjarrald, 2003; Mahrt, 2014; van Hooijdonk et al., 2015; Monahan et al., 2015; Vercauteren and Klein, 2015; Acevedo et al., 2016; Vignon et al., 2017b; Abraham and Monahan, 2019a, b, c, hereafter AM19a, AM19b, and AM19c). In this classification scheme the wSBL is characterised by weak stratification, strong wind and shears which produce sufficient turbulence kinetic energy (TKE) to sustain continuous turbulence and vertical mixing despite the stable stratification (e.g. van de Wiel et al., 2012). The vSBL is characterised by strong stratification, low wind speeds, and weak or intermittent turbulence such that vertical coupling of the atmospheric layers weakens. Very stable boundary layers are also sometimes found to display so-called upside down turbulence, in which TKE is generated aloft by strong shears and then transported downwards. Observational data as well as simulations show that to a good approximation in horizontally homogenous conditions the wSBL conforms to the

classical understanding of turbulence in the atmospheric boundary layer, with turbulence quantities decreasing with height and near-surface profiles which are well-described by Monin-Obukhov similarity theory (MOST; e.g. Sorbjan, 1986; Mahrt, 1998a, b, 2014; Pahlow et al., 2001; Grachev et al., 2005, 2013). In the vSBL, on the other hand, turbulence profiles can decouple from the surface (Banta et al., 2007) and MOST breaks down (e.g. Derbyshire, 1999; Banta et al., 2007; Williams et al., 2013; Mahrt, 2011; Optis et al., 2015). Regime structures and transitions are poorly represented in weather and climate models, due both to coarse resolution (vertical and horizontal) and to an imperfect understanding of the diverse physical processes governing the SBL, particularly with regard to the vSBL to wSBL transitions (e.g. Holtslag et al., 2013; Mahrt, 2014). In this study we analyse how well the statistics of SBL regime occupation and regime transitions can be described by a two-regime Markovian system, with the goal of using this information to develop a **prototype explicitly** stochastic parameterisations of turbulence in the SBL for models of weather and climate.

As transitions between the two SBL regimes are a common feature of SBL dynamics around the globe (AM19b) a representation of the effect of these dynamics in weather and climate models is needed. The regime transitions, however, are associated with a range of different mechanisms. Over land, the wSBL to vSBL transition (which for simplicity we denote the collapse of turbulence even though turbulence does not cease entirely) is normally caused by radiative cooling at the surface increasing the inversion strength and suppressing vertical turbulent fluxes of momentum and heat. This process is relatively well understood and has been examined using conceptual and idealised single column models (van de Wiel et al., 2007, 2017; Holdsworth et al., 2016; Holdsworth and Monahan, 2019; Maroneze et al., 2019, accepted in Q. J. Royal Meteorol. Soc.), or direct numerical simulations of stratified channel flows (Donda et al., 2015; van Hooijdonk et al., 2017) and atmospheric boundary layers (e.g. Flores and Riley, 2011; Ansorge and Mellado, 2014). Radiative cooling leads to very shallow boundary layers which are typically not resolved well in large-scale circulation models. Another mechanism for the wSBL to vSBL transition of particular importance over water is the advection of warm air aloft (AM19c), producing vSBL conditions which are not as shallow as those driven by radiative fluxes.

The vSBL to wSBL transition (which we denote the recovery of turbulence) is less well-understood. Mechanisms by which turbulence recovers include the build-up of shear resulting in instabilities, or an increase in cloud cover weakening the stratification through increasing the downwelling longwave radiation (AM19b). Another potential class of processes initiating these transitions is associated with intermittent turbulent events (e.g. Mahrt, 2014, and references within) which have been found to dominate the turbulent transport in vSBL conditions (Nappo, 1991; Coulter and Doran, 2002; Doran, 2004; Basu et al., 2006; Acevedo et al., 2006; Williams et al., 2013). Intermittent turbulence arises from a range of different phenomena such as breaking gravity waves or solitary waves (Mauritsen and Svensson, 2007; Sun et al., 2012), density currents (Sun et al., 2002), microfronts (Mahrt, 2010), Kelvin-Helmholtz instabilities interacting with the turbulent mixing (Blumen et al., 2001; Newsom and Banta, 2003; Sun et al., 2012), or shear instabilities induced from internal wave propagation (Sun et al., 2004; Zilitinkevich et al., 2008; Sun et al., 2015). It has also been suggested from direct numerical simulations that intermittency can arise as an intrinsic mode of the non-linear equations in the absence of external perturbations of the mean flow (Ansorge and Mellado, 2014). Regardless of which process causes the recovery of turbulence, all phenomena are subgrid-scale in state-of-the-art weather and climate models and are typically not included explicitly through process-based deterministic parameterisations.

Although processes in the SBL have been extensively studied, substantial errors of SBL representation persist in weather and climate models (Dethloff et al., 2001; Gerbig et al., 2008; Bechtold et al., 2008; Medeiros et al., 2011; Kyselý and Plavcová, 2012; Tastula et al., 2012; Sterk et al., 2013; Bosveld et al., 2014; Sterk et al., 2015). Misrepresentation of the SBL includes unrealistic decoupling of the atmosphere from the surface (due to misrepresentations of TKE in the vSBL) resulting in runaway surface cooling (Mahrt, 1998b; Walsh et al., 2008), underestimation of the wind turning with height within the boundary layer (Svensson and Holtslag, 2009), overestimation of the boundary layer height (Bosveld et al., 2014), underestimated low level jet speed (Baas et al., 2009), and underestimation of near-surface wind speed and temperature gradients or their diurnal cycle (Edwards et al., 2011).

Accurate simulations of these near-surface properties is particularly important for global and regional weather forecasts of vertical temperature structures, for instance, which control the formation of fog and frost (Walters et al., 2007; Holtslag et al., 2013). More accurate simulations of the SBL regime behaviour are also important for better representations of surface wind variability and wind extremes (He et al., 2010, 2012; Monahan et al., 2011); simulation and assessment of pollutant dispersal, air quality (Salmond and McKendry, 2005; Tomas et al., 2016), harvesting of wind energy (Storm and Basu, 2010; Zhou and Chow, 2012; Dörenkämper et al., 2015); and agricultural forecasts (Prabha et al., 2011; Holtslag et al., 2013).

Global and regional weather and climate models often use an artificially enhanced surface exchange under stable conditions in order to improve simulations of the large-scale flow (Holtslag et al., 2013). This approach has led to the introduction of long-tailed stability functions and minimum background TKE values not justifiable by observations. In such representations, turbulence is artificially sustained under very stable conditions and the two-regime characteristic of the SBL is suppressed, biasing near surface winds and temperature profiles. Without such parameterisations the nocturnal boundary layers can experience a single turbulence collapse which persists for the entire night. Although the long-tailed stability functions in relatively coarse-resolution models are designed to mimic the gridbox-mean of fluxes over many subgrid-scale wSBL and vSBL patches, with increasing horizontal and vertical resolution more accurate process-based parameterisations are necessary. The occurrence of vSBL to wSBL transitions does not appear to depend deterministically on internal or external state variables (AM19a,b), indicating that parameterisations of the effects of these kinds of transitions in weather and climate models may be required to be explicitly stochastic (e.g. He et al., 2012; Mahrt, 2014). In particular, phenomena such as intermittent turbulence events will likely rely on stochastic parameterisations as their structure and propagation are found to be only weakly-dependent on the mean states (e.g. Rees and Mobbs, 1988; Lang et al., 2018). Stochastic subgrid-scale parameterisations to describe the physically different conditions in the SBL have been proposed to help capture the missing variability in the SBL and improve both climate mean states and forecast ensemble spread (e.g. He et al., 2012; Mahrt, 2014; Nappo et al., 2014; Vercauteren and Klein, 2015). Vercauteren and Klein (2015) propose, for instance, an additional Markovian system to switch between times of strong and weak influences of short-timescale but non-turbulent motions on TKE production in the vSBL, causing regime transitions.

In AM19a,b,c it was demonstrated that hidden Markov model (HMM) analysis of Reynolds-averaged mean states can be used as a tool to analyse the SBL regimes at tower sites in many different settings. Independent of the surface type, the climatological setting, or the complexity of the surrounding topography, two distinct regimes in the state variable spaces of

Reynolds-averaged mean states and turbulence are evident. As the HMM analyses provide climatological (that is, based on long-term statistics) transition probability matrices for a two-regime Markovian system, a natural approach to developing stochastic parameterisations of SBL regime dynamics is to investigate if these can be based on ‘freely-running’ stationary Markov chains (FSMC) using these transition matrices. The first goal of this study is to determine if climatological Markovian transition probability matrices, which are by construction independent of the state of the SBL, are adequate for simulations of the SBL regime dynamics. While the HMM analyses presented in AM19a assume stationary Markov regime dynamics, statistical analyses of the estimated regime sequences show clear evidence of elevated probability of turbulence collapse close to sunset (AM19b). Furthermore, probability distributions of event durations demonstrate a localised maximum corresponding to a recovery time of on average one to two hours after transitions in which a subsequent transition is unlikely, indicating non-Markov behaviour (AM19b). Because of these non-stationary and non-Markov behaviours, a FSMC will never exactly capture all aspects of SBL regime dynamics. However, it might be sufficient to reproduce most statistics of interest.

In order to investigate the potential of an FSMC-based parameterisation, we first analyse how well they can characterize the HMM-based regime statistics. As part of this analysis we consider the sensitivity of the regime sequence estimated by the HMM to perturbations of the persistence probabilities, allowing for a quantification of what ranges of persistence probabilities accurately describe SBL regime statistics in HMM analyses. By comparing this sensitivity analysis with a sensitivity analysis of regime statistics to varying persistence probabilities in a FSMC we quantify what ranges of persistence probabilities are consistent with both SBL regime statistics derived from an HMM analysis and SBL regime statistics simulated in a FSMC. As we demonstrate that FSMCs cannot simulate all SBL regime statistics of interest, we then consider state-dependent SBL regime transition probabilities. Finally, we develop a pragmatic prototype of an explicitly stochastic parameterisation using the derived state-dependent transition probabilities and present preliminary tests in the idealised single column model (SCM) of Holdsworth and Monahan (2019). The study is organised as follows. First a very short review of the observational data used in the HMM analysis is given in section 2, followed by a brief review of the HMM application to the SBL (section 3). Results of simulating statistics in FSMC are shown in section 4, followed by the description of the prototype state-dependent stochastic parameterisation and test simulations in section 5. Conclusions follow in section 6.

25 **2 Data**

The observational data used in this study have been discussed in detail in AM19a. We present here a short summary of the data. Observational data sets from nine different research towers measuring standard Reynolds-averaged meteorological state variables with a time resolution of 30 minutes or finer are considered (Table 11). The observational levels of wind speeds and temperatures correspond to the reference state variable sets which are used in the HMM analyses to classify the data into SBL regimes (cf. AM19a, Table 11). Substantial differences among the nine experimental sites exist in terms of their surface conditions, surrounding topography, and their meteorological setting. As a simple classification scheme, we distinguish between land-based, glacial-, and sea-based stations.

The land-based stations can be further clustered into different subsets. Both the Cabauw and Hamburg towers lie in flat, humid, grassland areas, although the Hamburg tower is affected by the large metropolitan area of Hamburg. The Karlsruhe tower is located in the Rhine valley, a rather hilly, forested area. The American sites, Boulder and Los Alamos, are located in relatively arid settings and are strongly affected by the surrounding topography of the Rocky Mountains.

- 5 **The DomeC observatory, the single glacial-based station, is located in the interior of Antarctica and is influenced by completely different surface conditions including high albedo and low roughness length.**

The sea-based stations are the offshore research platforms *Forschungsplattform in Nord- und Ostsee* (FINO), located in the German North and Baltic Seas. These sites are characterized by relatively homogeneous local surroundings and a large surface heat capacity. At the FINO towers nights with statically unstable conditions (defined as nights with two or more unstable
10 datapoints in a night) are excluded as under these conditions wind speed measurements are unreliable (Westerhellweg and Neumann, 2012). Furthermore, at FINO-1 nights with primary wind directions between 280 and 340 degrees are excluded due to mast interference effects in the data. At the other stations such an exclusion is not necessary as three wind measurements with 120 degree separation are taken at each level.

3 Brief summary of the hidden Markov model

15 We now present a brief overview of the HMM analysis with application to the SBL (Monahan et al., 2015, AM19a). An in-depth description of HMM analysis can be found in Rabiner (1989).

We use the HMM to systematically characterize regime behaviour in the SBL from observed data. The HMM assumes that underlying the observations is an unobserved, or hidden, discrete Markov chain ($\mathbf{X} = \{x_1, x_2, \dots, x_T\}$). The analysis estimates the regime-dependent parametric probability density distribution (pdf) of the observations (described by the parameter set λ),
20 the transition probability matrix \mathbf{Q} , and a most likely regime path of the Markov chain (known as the Viterbi Path, VP). We associate the different states of the Markov chain with the SBL regimes (wSBL and vSBL). In our analysis we use observations of the three-dimensional vector consisting of the Reynolds-averaged vertically-averaged mean wind speed, wind speed shear, and stratification to define the HMM input vector \mathbf{Y} . A detailed justification of this observational input dataset is presented in AM19a. The HMM estimation algorithm makes use of the following assumptions:

- 25 1. Markov assumption: the current regime value i_t at x_t depends exclusively on the previous regime of x_{t-1} , so:

$$P(x_t = i_t | x_{t-1} = i_{t-1}, x_{t-2} = i_{t-2}, \dots, x_0 = i_0) = \mathbf{Q}_{i_t i_{t-1}} \quad \forall t \quad \text{with } i \in \{0, 1\}, \quad (1)$$

where the dynamics of the SBL are governed by \mathbf{Q} (a 2×2 matrix corresponding to the wSBL and vSBL, respectively) such that $\sum_{i_t} \mathbf{Q}_{i_t i_{t-1}} = 1$.

- 30 2. Independence assumption: conditioned on \mathbf{X} , values of \mathbf{Y} are independent and identically distributed variables resulting in a probability of the observational data sequence of

$$P(\mathbf{Y}, \mathbf{X} | \Lambda) = \pi_i p(\mathbf{y}_0 | x_0 = i_0, \lambda_{i_0}) \prod_{t=1}^T \mathbf{Q}_{i_t i_{t-1}} p(\mathbf{y}_t | x_t = i_t, \lambda_{i_t}) \quad \text{with } i \in \{0, 1\} \quad (2)$$

where $\Lambda = \{\lambda_i, \pi_i, \mathbf{Q}\}_{i \in \{0,1\}}$ is the full set of parameters of the HMM, for which $\{\lambda_i\}_{i \in \{0,1\}}$ is the parameter set describing the regime-dependent pdfs of \mathbf{y}_t (taken to be Gaussian mixture models as in AM19a), and π_i is the probability that x_0 is in regime i (wSBL or vSBL).

3. Stationarity **assumption**: this analysis assumes that \mathbf{Q} and $\{\lambda_i\}_{i \in \{0,1\}}$ are time-independent.

5 The goal of the HMM analysis is to estimate Λ from \mathbf{Y} . Starting from the probability of the observational time series conditioned on the parameters $P(\mathbf{Y}|\Lambda)$ and applying Bayes theorem to obtain $P(\Lambda|\mathbf{Y})$, the problem reduces to a maximum-likelihood estimation which can be iteratively solved to find local maxima via the expectation maximisation algorithm (Dempster et al., 1979). Having estimated Λ , the most likely regime sequence (the VP) can be calculated. **Regime occupation and transition statistics can then be obtained through analysis of the VP.** The estimation of the parameters in the expectation-
10 maximisation scheme for our analysis is described in detail in Rabiner (1989).

One limitation of the HMM model considered is that it assumes stationary statistics, However, nonstationarities linked to the **diurnal** cycle and seasonal variability are present in the regime statistics of the SBL (cf. next section, AM19b). Generalizations exist which can account for nonstationarities, such as nonhomogeneous HMMs (Hughes et al., 1999; Fu et al., 2013) **which condition transition probabilities on the state of external variables.** Other clustering techniques such as the finite-element vari-
15 ational approaches also relax the stationarity assumptions (e.g. Franzke et al., 2009; Horenko, 2010; O’Kane et al., 2013). In particular, the finite-element, bounded-variation, vector autoregressive factor method (FEM-BV-VARX) includes both autoregressive dynamics within each regimes and a modulation of regime dynamics to external drivers. For instance, Vercauteren and Klein (2015) were able to use this model to identify different regimes of interaction between submesoscale motions and the turbulence. However, as our analyses find no clear relationship between external drivers (geostrophic wind and cloud cover)
20 and transitions between regimes of Reynolds-averaged variables (AM19b), we consider stationary HMM analysis in this study in order to investigate the simplest possible approach to a stochastic parameterisation of turbulence under SBL conditions. Using such a relatively simple parameterisation allows us to determine where additional complexity is warranted and assess how well the dynamics are approximated by stationary Markovian systems.

4 SBL regime statistics based on ‘freely-running’ Markov chains

25 To be useful as the basis of new parameterisations of turbulent fluxes in the SBL, FSMCs should model SBL regime statistics accurately. The statistics we focus on are the event durations and the probabilities of each of: the occurrence of very persistent nights, of the occurrence of at least one transition within a night, and of multiple transitions within a night. Our reference FSMC models use transition matrices \mathbf{Q}_{ref} obtained from HMM analyses in AM19a (Table 11). In the HMM analysis, the matrix \mathbf{Q} can be held fixed at prescribed values while other parameters and the VP are estimated. Repeating HMM analyses
30 using such fixed \mathbf{Q} perturbed from \mathbf{Q}_{ref} , we investigate the sensitivity of the regime statistics of corresponding VPs relative to their reference VP_{ref} . Because the estimated VP is constrained by the observations, its statistics may differ considerably from a FSMC using the same \mathbf{Q} . Evaluating the regime statistics in FSMC for a range of different \mathbf{Q} determines the ranges of

persistence probabilities for which SBL regime statistics of a FSMC match those of VP_{ref} . Mathematical expressions used to compute the regime statistics of a FSMC using a given Q are presented in Appendix A. These calculations require specification of the lengths of the nights. As the tower sites are located in the midlatitudes, we use a range of nighttime durations between 8 and 15 hours. In this section we do not consider the glacial-based station, DomeC in Antarctica. Because the duration of the polar nights is much longer than nights at the other midlatitude stations considered, direct comparisons of regime occupation statistics within individual nights are not meaningful.

4.1 Comparison of VP_{ref} and FSMC statistics

For a FSMC (using Q_{ref} in Eqns. A1 and A2), the frequency of the occurrence of very persistent wSBL nights decreases monotonically with the length of the night (Figure 11). Occurrence probabilities of very persistent wSBL nights from the FSMC match those of VP_{ref} in summertime (nights of duration 8 to 10 hours) but are otherwise underestimated. For nights lasting longer the FSMC underestimates their occurrence. The increase in occurrence probability in VP_{ref} with increasing night length is consistent with larger synoptic-scale variability and stronger mechanical generation of turbulence in winter, but is not accounted for in a FSMC. The occurrence probabilities of very persistent vSBL nights decrease with increasing length of night in VP_{ref} , consistent with an increase in mean pressure gradient force. While the FSMC also shows this behaviour, it systematically underestimates the observed occurrence of very persistent vSBL nights.

In VP_{ref} the probability of at least one wSBL to vSBL or vSBL to wSBL transition occurring within a night shows no systematic dependence on the length of the night across the tower sites (Figure 12). In contrast, the occurrence probability of at least one transition in a FSMC (Eqns. A3 and A4) increases with the length of the night, and is larger than the VP_{ref} at all sites (Figure 12, lower panels). The overestimation of turbulence recovery events by the FSMC is slightly larger than that of turbulence collapse events at land-based stations, while the opposite is true at sea-based stations.

The probabilities of the occurrence of a recovery event subsequent to a turbulence collapse in the FSMC (Eqns. A6 and A8, Figure 13) agree better with those of VP_{ref} than do the probabilities of the overall occurrence of at least one wSBL to vSBL transition (Figure 12). Both VP_{ref} and FSMC occurrence probabilities increase with the length of the night, at about the same rate. At land-based stations the VP_{ref} has fewer subsequent turbulence recovery events than expected from a FSMC, and at sea-based sites more are observed than predicted by a FSMC. Distributions of wSBL to vSBL transitions subsequent to recovery events in a FSMC and the VP_{ref} are generally similar with slightly better agreement in summer than during winter (Figure 13, right panels).

The occurrence of subsequent transition events is related to event durations in the vSBL and wSBL. For both types of events, the duration pdfs display clear maxima between one and two hours after preceding transitions, demonstrating that the occurrence of subsequent transitions most often occurs after some recovery period (Figure 14). No two-regime FSMC can account for these recovery periods because event duration pdfs in the FSMC always decay monotonically (equations A5 and A7 using 12 hour nighttime durations). After the initial recovery period, however, event duration pdfs are generally close in the VP_{ref} and FSMC, resulting in a generally good agreement of mean event durations. The qualitative shape of the event duration pdfs is insensitive to season, although during winter the probabilities of longer events increase (longer nights allow more time

for longer events to occur). Consistently, different nighttime durations in the FSMC change the slope of the exponentially decreasing probability functions (steeper and shallower for respectively shorter and longer nights), however, the substantial differences to pdfs estimated from VP_{ref} remain

The results above demonstrate the existence of at least two aspects of the regime statistics which qualitatively cannot be accounted for by a two-regime FSMC: non-stationary and non-Markov behaviour. While many other regime statistics follow qualitatively the behaviour of a FSMC, quantitative differences between the statistics of VP_{ref} and FSMCs using Q_{ref} are substantial. As values on the diagonal of Q_{ref} are close to one (Table 11), the theoretical regime statistics calculated from the FSMC are highly sensitive to these values (cf. Eqns. A1-A8). Therefore, we now investigate the sensitivity of VP to perturbed Q to determine if biases in the SBL regime statistics of the FSMC can be reduced by modest changes of Q.

4.2 Sensitivity of the VP to perturbed persistence probabilities

We consider the sensitivity of the VPs to changes of the persistence probabilities ($Q_{i_t i_{t-1}} = P(i_{t-1} \rightarrow i_t)$ with $i_t = i_{t-1}$ and $i \in \{\text{wSBL}, \text{vSBL}\}$) by perturbing Q from the reference value, holding it fixed, and repeating the HMM analysis. In order to assess if the perturbed VPs are consistent with VP_{ref} we consider first the occupation consistency between the two (the fraction of time in which both VPs are in the same regime). As in AM19a, we then assess the consistency of the timing of transitions (simultaneity of transitions in the reference and perturbed VPs) as well as the representation of very persistent nights. These various metrics are then combined to obtain the total VP consistency. For this part of the analysis, we focus on the Cabauw tower data as we have analysed these data extensively in AM19a. The same qualitative results are found using all tower station data we have considered (not shown).

The estimated VP is robust to substantial changes in Q, with an occupation consistency of more than 90 % obtained for ranges of wSBL and vSBL persistence probabilities between 0.5 and about 0.9999 (Figure 15). Agreement at the 99 % level is found for persistence probabilities between approximately 0.9 and 0.9999. Accurate representation of the timing of transitions is found for both a broad range of low persistence probabilities and for a small range of persistence probabilities between 0.96 to 0.99. The fact that the accuracy of the transitions is above 99 % if both persistence probabilities are below 0.5 (regime transitions in a single step are more probable than remaining in the regime) is a consequence of the high frequency of modelled transitions improving the ability to capture individual transitions in VP_{ref} (at the expense of modelling far too many transition events). Because regime transitions are relatively rare, the physically meaningful range of persistence probabilities corresponds to relatively large values of both. The accuracy of the occurrence of very persistent wSBL nights in the perturbed VP is best for high $P(\text{wSBL} \rightarrow \text{wSBL})$ and is weakly sensitive to $P(\text{vSBL} \rightarrow \text{vSBL})$. This result is not surprising as the high wSBL persistence probability ensures that the majority of very persistent wSBL nights as estimated by VP_{ref} are captured. This measure is unaffected by any underestimate of the occurrence of very persistent vSBL nights. Complimentary results are found for the occurrence of very persistent vSBL nights.

Each of the five consistency measures discussed capture distinct aspects of agreement between the reference and perturbed VPs. We define total consistency relative to VP_{ref} as each of the five described VP consistencies exceed a specific threshold. At Cabauw, a 99 % total consistency can be achieved for $P(\text{wSBL} \rightarrow \text{wSBL})$ between approximately 0.97 and 0.99 and

$P(\text{vSBL} \rightarrow \text{vSBL})$ between 0.98 and 0.99 (Figure 15, bottom right panel). If only a 95 % total VP consistency is required, $P(\text{wSBL} \rightarrow \text{wSBL})$ and $P(\text{vSBL} \rightarrow \text{vSBL})$ can range approximately between 0.95 and almost 1.

The sensitivity analysis of the estimated regime occupation sequence to changes in Q values reveals that reasonably accurate regime statistics can be obtained over a relatively large range of persistence probabilities. **We now turn return to FSMC calculations using the ranges of Q where the total VP consistency exceeds 95 %** to assess if a common range of persistence probabilities exists where **statistics of VP_{ref} and FSMC** are consistent.

4.3 Sensitivity of SBL regime statistics to changing persistence probabilities in a FSMC

As discussed above, calculations of the theoretical values of SBL regime statistics from a **FSMC** require specifying the duration of the night. **To compare statistics from VP_{ref} and FSMC we define three night time durations representative of individual seasons (Table 12). The statistics from VP_{ref} for the individual towers and seasons are listed in Table 13. To account for sampling uncertainty in the SBL regime statistics as estimated from VP_{ref} , we consider occurrence probabilities in a 10 % error range ($\pm 5 \%$) around the values from VP_{ref} .**

Similar to what was found at Cabauw, across all land-based stations the perturbed VP is not very sensitive to the values of Q and a relatively broad range of persistence probabilities allows for a 95 % total VP consistency in the HMM analyses (Figure 16; grey isolines). The persistence probabilities corresponding to the most likely VPs are reasonably similar across the different stations. In Figure 16 the solid, dashed, and dotted lines respectively correspond to **persistence probabilities resulting in FSMC probabilities of at least one transition in a night equal to, 5 % below, and 5 % above the VP_{ref} values** (wSBL to vSBL in red; vSBL to wSBL in black). The range of persistence probabilities for which the **FSMC** models the **VP_{ref}** occurrence probabilities of very persistent nights within a 10 % uncertainty band is displayed by a **red shaded rectangle with a mark for the exact VP_{ref} statistics.**

Despite accounting for non-stationarity by considering nights of different lengths separately, in general no ranges of persistence probabilities in any season can be identified for which FSMCs are able to model all SBL regime statistics within our imposed uncertainty range. Only at Cabauw in wintertime and Hamburg in spring or autumn does such a range of persistence probabilities exist.

In order to model only a subset of SBL regime statistics (such as the occurrence of SBL regime transitions or very persistent nights) accurately in a FSMC, the required persistence probability values generally fall outside the region of high total VP consistency between the reference and perturbed VPs. This fact is true for all seasons.

At sea-based stations the range of persistence probabilities that ensures good agreement between the VP_{ref} and the perturbed VPs is substantially larger than for land-based stations (not shown). The total VP consistency exceeds 95 % for regime persistence probabilities ranging from approximately 0.92 to 0.99. Nonetheless, similar to land-based stations, no persistence probability range can be identified which allows a FSMC to simulate all SBL regime statistics accurately. Again, to obtain only specific SBL regime statistics, ranges of persistence probabilities are required which generally exceed the values assuring good agreement between the reference and perturbed VPs.

The fact that a FSMC is not able to account for all regime statistics (with or without seasonally varying Q) motivates the consideration of other approaches to the parameterisation of regime dynamics. In particular, the use of state-dependent transition probabilities is supported by the relatively well-understood control of the internal SBL dynamics on wSBL to vSBL transitions (e.g. Acevedo et al., 2019; Maroneze et al., 2019, AM19b, AM19c), including the role of surface energy coupling (van de Wiel et al., 2017; Holdsworth and Monahan, 2019). In the next section we present a prototype of such a parameterisation.

5 Stochastic parameterisation for SBL regime dynamics

In this section, we develop a prototype explicitly stochastic parameterisation for numerical weather prediction and climate models and test it using an idealised SCM. We first consider the state dependence of transition probabilities on the basis of VP_{ref} for the simulation of a two-value (wSBL or vSBL) discrete SBL regime occupation variable (S). After having estimated functional forms for these conditional probabilities from fits to data, a parameterisation of episodic enhancement of eddy diffusivity by intermittent turbulence bursts is developed. Finally, the application of this parameterisation in the SCM is presented. We emphasize the fact that the explicitly stochastic parameterisation and its tests presented here are intended to be a proof of concept. A formal validation of model experiments against observational data, including systematic sensitivity analyses of the free parameters and an implementation in a more complex single column model will be the subject of a future study.

5.1 State-dependent transition probabilities

The Richardson number (Ri) is often used in parameterisations of stratified boundary layer turbulence, and as such is a natural candidate on which to condition probabilities of transitions between states of S . For instance, we expect physically that $P(\text{wSBL} \rightarrow \text{vSBL}|Ri)$ should be small for small Ri , but should increase to virtual certainty for sufficiently large Ri .

Due to their coarse vertical sampling, the Reynolds-averaged observational tower data considered only allow for a characterisation of finite differenced approximations to Ri , defined as the bulk Richardson number (Ri_B):

$$Ri_B = \frac{g}{\bar{\Theta}}(h - s) \frac{\Theta_h - \Theta_s}{W_h - W_s}, \quad (3)$$

where g is the acceleration due to gravity, $\bar{\Theta}$ the mean background potential temperature, h the height of the upper measurement and s the lower measurement height near the surface, and Θ and W are respectively the potential temperature and wind speed (with heights indicated by subscripts).

To assess the relationship between Ri_B and transition probabilities (and in particular the robustness of this relationship across different locations) we investigate composites of its evolution during regime transitions at the various tower sites described in section 2. These composites, centred on the time of transitions and extending 90 minutes before and after, provide information about the average behaviour of Ri_B across transitions. Such composites do not distinguish differences between individual events which may be important for a detailed physical understanding of a specific transition. Furthermore, composite changes may be less sharp than individual ones, due to variations in transition timing below the averaging scale of the data considered.

Across all land- and glacial-based stations Ri_B measured between each observational height and the surface systematically increases (decreases) during turbulence collapse (recovery) events (Figure 17, columns one and three). At sea-based sites changes in Ri_B are not evident. The weak signal in Ri_B at sea-based stations is likely related to the fact that the lowest observational levels are much higher than at other stations (30 m above mean sea level).

- 5 In order to compare across all tower sites we concentrate on Ri_B between about 100 m and 10 m ($Ri_B(100, 10)$) for land-based stations. Because of the very shallow inversion at this location, at DomeC we use Ri_B between 4 m and 1 m (cf. AM19c). The distributions of $Ri_B(100, 10)$ show that not only do the mean and median show a systematic behaviour across regime transitions, but so too does the interquartile range (Figure 17, columns two and four). Consistent with previous results the distributions at sea-based stations across transitions do not change.
- 10 The $P(wSBL \rightarrow vSBL|Ri_B)$ estimated from using the VP_{ref} (binned by Ri_B increments of 0.02) shows low transition probabilities across all tower sites (well below 0.01) for Ri_B smaller than about 0.1 (Figure 18, upper left panel). For Ri_B larger than 0.1, $P(wSBL \rightarrow vSBL|Ri_B)$ increases linearly at the land-based and glacial-based station to about 0.6 beyond which wSBL conditions are unsustainable. Consistent with the composites in Figure 17, $P(wSBL \rightarrow vSBL|Ri_B)$ at sea-based stations is independent of Ri_B .
- 15 At land-based stations, $P(vSBL \rightarrow wSBL|Ri_B)$ demonstrates that vSBL conditions below Ri_B 0.1 are unsustainable (Figure 18, upper right panel). Above $Ri_B \simeq 0.1$ values of $P(vSBL \rightarrow wSBL|Ri_B)$ do not approach zero and are approximately independent of Ri_B . However, $P(vSBL \rightarrow wSBL|Ri_B)$ exhibits considerable variability with no evident systematic behaviour across stations. If implemented into a parameterisation, the approximately state-independent $P(vSBL \rightarrow wSBL|Ri_B)$ would result in turbulence recovery transition statistics decoupled from the flow or stratification profiles. As such, it could not account
- 20 for the recovery time evident in the observed event duration pdfs. This fact, along with the fact that the conditional dependence of wSBL to vSBL transitions is entirely different over land than it is over the ocean, suggests that conditioning the transition probabilities on Ri_B is not appropriate.

As an alternative to conditioning on Ri_B , we now consider conditioning transition probabilities on stratification. At all sites except DomeC, we represent the stratification by $\Theta_{100} - \Theta_s$. Due to the very shallow boundary layers at DomeC potential

25 temperature differences between about 4 m and the surface (which demonstrate comparable stratification value changes during transitions) are considered. Although the stratification alone does not describe the full dynamical stability of the flow it is among the state variables which display the largest changes across regime transitions (cf. van de Wiel et al., 2017, and AM19c). Moreover, HMM analyses of the stratification alone have been shown to accurately capture the VP_{ref} (cf. AM19a). Across the 90 minutes before and after transitions, not only do the composites of stratification demonstrate clear changes (cf. AM19c) but

30 the entire probability distribution shifts (Figure 19).

The derived transition probabilities conditioned on $\Theta_{100} - \Theta_s$ as estimated from VP_{ref} (binned by increments of 0.2 K) demonstrate qualitatively similar behaviour at all stations (Figure 18, second row). In contrast to conditioning on Ri_B , conditioning transition probabilities on stratification does not show marked differences between land- and sea-based stations. The $P(wSBL \rightarrow vSBL|\Theta_{100} - \Theta_s)$ demonstrates an almost linear increase with increasing stability across all tower sites. The

35 turbulence recovery transition, on the other hand, shows very low $P(vSBL \rightarrow wSBL|\Theta_{100} - \Theta_s)$ above about 2-3 K but in-

creases rapidly for weaker inversion strengths. To build a state-dependent parameterisation for S conditioned on stratification, conditional transition probabilities discussed above are fit to functional forms. As the wSBL cannot be sustained for strong inversions nor a vSBL for weak inversions (Figure 18, second row), transition probabilities for such conditions are set to one. The functional forms for the stratification-dependent transition probabilities are

$$5 \quad P(\text{wSBL} \rightarrow \text{vSBL} | \Theta_{100} - \Theta_s) = \begin{cases} \alpha (\Theta_{100} - \Theta_s) + \delta & \text{for } \Theta_{100} - \Theta_s < 3K \\ 1 & \text{for } \Theta_{100} - \Theta_s \geq 3K \end{cases} \quad (4)$$

and

$$P(\text{vSBL} \rightarrow \text{wSBL} | \Theta_{100} - \Theta_s) = \alpha \tanh\left(\frac{\Theta_{100} - \Theta_s - \beta}{\gamma}\right) + \delta. \quad (5)$$

The best fit parameter and the RMSE for each station are listed in Table 14; the corresponding best-fit functions are shown in Figure 18 (second row). Those fits are similar enough to each other to allow for an assessment of the mean behaviour through
 10 all data for which the parameter sets are listed in Table 14 depicted in Figure 18 (third row, solid black line). Using the median parameter set or a best-fit through all data does not change the parameterisation substantially.

5.2 Stochastic forcing in the vSBL regime

As described in the introduction, state-of-the-art planetary boundary layer turbulence parameterisations are generally able to produce radiatively driven turbulence collapse. In contrast, mechanisms to explicitly generate the turbulence recovery are
 15 too weak or lacking in standard parameterisations. He et al. (2012) showed that a stochastic process representing the effects of intermittent turbulence events can be implemented as an extra source term in the prognostic TKE budget during vSBL conditions, such that these events episodically drive the vSBL into a turbulence active regime. In their approach, however, the generation of intermittent turbulence bursts did not depend on the state of the boundary layer. Here, we propose to introduce
 20 a new local variable, the two-value discrete SBL regime occupation variable S , tracking SBL regimes. At each time step the occurrence of a regime transition is determined randomly using the instantaneous state-dependent transition probabilities derived above. When S is in the vSBL additional stochastic forcing is added as a representation of the effect of intermittent turbulence bursts. These enhancements occur with random sizes and at random times, and are similar to a compound Poisson process. This approach can also account for the recovery time in the vSBL event durations.

Many models, including the one we consider, represent turbulence fluxes using first order closure. Here, we represent additional stochastic forcing by increasing the diffusivities of heat and momentum:
 25

$$K(t, z) = K_{SCM}(t, z) + \sum_k SF_k(t, z), \quad (6)$$

where K is the diffusivity for momentum and heat, K_{SCM} the diffusivity as determined by the standard SCM parameterisation (cf. Eqn. B7), and SF_k represents the effects of the k -th intermittent turbulence pulse parameterised as follows.

1. At each timestep the probability of the occurrence of an intermittent turbulence pulse is given by $\lambda_{SF} dt$, where λ_{SF} is
 30 its occurrence rate and dt the model timestep. If a turbulence pulse is determined to occur at time t_k , a random number

r is drawn from a uniform-distribution on $[0, R]$ representing the maximum strength of the burst SF_k , occurring at time

$$t_{w_k} = t_k + \tau_w.$$

2. The evolution of SF_k is split into growth and decay phases. The relatively short growth phase is introduced to avoid numerical instabilities, while the decay phase represents the dissipation of the intermittent turbulence pulse. Each SF_k is assumed to have a Gaussian profile in the vertical (which is intended to represent the localisation of the enhanced mixing in the region where the turbulence pulse occurs) given by

$$SF_k(t, z) = s_k(t) \exp\left(-\frac{(z - h_k(t))^2}{2\sigma_k^2(t)}\right). \quad (7)$$

3. The strength $s_k(t)$ increases from t_k until t_{w_k} according to a hyperbolic tangent function. Afterwards an exponential decay is prescribed with an eddy overturning timescale τ_e :

$$s_k(t) = \begin{cases} 0 & \text{for } t < t_k \\ 0.505 r \tanh\left(\frac{t - 0.5 \tau_w - t_{w_k}}{0.5 \tau_w} \tanh^{-1}\left(\frac{99}{101}\right)\right) + 0.505 r & \text{for } t_k \leq t < t_{w_k} \\ r \exp\left(-\frac{t - t_{w_k}}{\tau_e}\right) & \text{for } t \geq t_{w_k} \end{cases} \quad (8)$$

4. We assume the centre of the turbulence pulse, $h_k(t)$, to be initiated aloft (cf. AM19c, Figure 4) and to move exponentially towards the surface during the decay phase:

$$h_k(t) = \begin{cases} h_b & \text{for } t < t_{w_k} \\ (h_b - h_e) \exp\left(-\frac{t - t_{w_k}}{\tau_h}\right) + h_e & \text{for } t \geq t_{w_k} \end{cases}, \quad (9)$$

where h_b and h_e denote the heights of the centre of $SF_k(t, z)$ at the beginning and end of the turbulence pulse respectively, and τ_h is the vertical migration timescale.

5. The width of $SF_k(t, z)$, $\sigma_k(t)$, is assumed to increase until t_{w_k} according to a hyperbolic tangent function which is introduced to avoid numerical instabilities as for $s_k(t)$. The functional form ensures $\sigma_k(t)$ to grow at the same rate as $s_k(t)$. During its decay $\sigma_k(t)$ widens exponentially (representing the interaction of the turbulent patch with its surrounding) with a typical broadening timescale τ_σ :

$$\sigma_k(t) = \begin{cases} \frac{\sigma_w + 1}{2} \tanh\left(\frac{t - 0.5 \tau_w - t_{w_k}}{0.5 \tau_w} \tanh^{-1}\left(\frac{\sigma_w - 1}{\sigma_w + 1}\right)\right) + \frac{\sigma_w + 1}{2} & \text{for } t < t_{w_k} \\ (\sigma_w - \sigma_e) \exp\left(-\frac{t - t_{w_k}}{\tau_\sigma}\right) + \sigma_e & \text{for } t \geq t_{w_k} \end{cases}, \quad (10)$$

where σ_w and σ_e are the widths of the turbulence pulse at respectively the time of its maximal strength and end of its lifecycle.

As indicated by Eqn. 6, the effects of multiple overlapping turbulence bursts are taken to be additive. Thus, we assume no interaction between successive turbulence bursts. Below we test the parameterisation in an idealised SCM. The values for the parameters in the stochastic forcing parameterisation as used in the SCM experiments are listed in Table 15.

5.3 SCM experiments with explicitly stochastic parameterisation

5 The SCM we use to test the parameterisation is described in van Hooijdonk et al. (2017) and Holdsworth and Monahan (2019). The governing equations of the SCM are presented in detail in Appendix B. In this study we consider the upper boundary of the model, at which we impose the boundary condition that the flow is geostrophic with a speed of 6 m s^{-1} , to be fixed at 5000 m. The lower boundary of the model domain is determined by the momentum roughness length which is set at $z_0 = 0.001 \text{ m}$ over a dry sand surface with density $\rho_s = 1600 \text{ kg m}^{-3}$, specific heat capacity $c_s = 800 \text{ J kg}^{-1} \text{ K}^{-1}$ and thermal conductivity $\lambda_s = 0.3 \text{ W m}^{-1} \text{ K}^{-1}$. Furthermore, we assume clear sky conditions.

The explicitly stochastic parameterisation described above results in SBL transitions that are qualitatively in agreement with observations. An example realisation is presented in Figure 110. In this realisation radiative cooling leads initially to a steady increase in stratification and flow stability. Once the vSBL is established (around simulation hour 2) turbulence pulses occur (none of which are individually sufficient to initiate a vSBL to wSBL transition). These turbulence pulses result in heat fluxes slightly larger than observed but of the right order of magnitude (eg. Doran, 2004). The occurrence of multiple smaller turbulence pulses between simulation hours 6-7.5 slowly erodes the stratification until it is sufficiently weakened that a vSBL to wSBL transition becomes sufficiently likely that such a transition occurs. Consistent with observations the simulated vSBL to wSBL transition lags behind the occurrence of the last turbulence burst (AM19c). After the wSBL is established (about simulation hour 7.5) the stratification begins to increase again and a subsequent turbulence collapse occurs approximately 1.5 hours after the recovery event. This recovery time is very close to the peak in the pdf of the wSBL event duration (cf. Figure 14) providing further evidence that these recovery periods in the wSBL are related to the internal dynamics of the wSBL.

Structures of wind and temperature profiles during vSBL to wSBL transitions resemble those of observations (cf. AM19c). Turbulence pulses lead to warming in the lowest 40 m of the boundary layer as turbulent sensible heat fluxes transport warm air from layers between 50 to 150 m towards the surface (Figure 110, middle panels). Enhanced vertical momentum transport results in the near-surface winds first increasing, and then decreasing (as a result of enhanced surface momentum flux; Figure 110, bottom panels). The relative magnitudes of the initial wind speed increase and subsequent decrease are sensitive to the height and width of SF_k (not shown). As the turbulence pulses decrease the stratification, boundary layer heights increase. These results demonstrate that an explicitly stochastic model with state-dependent transition probabilities and a representation of intermittent turbulence pulses in the vSBL can produce regime transitions that are in qualitative agreement with observations.

30 6 Discussion and Conclusions

Recent studies have demonstrated that hidden Markov model (HMM) analysis is an effective tool to classify the nocturnal boundary layer (SBL) into weakly stable (wSBL) and very stable (vSBL) conditions (Monahan et al., 2015, AM19a, AM19b,

AM19c). One goal of this study is to investigate if a two-regime ‘freely-running’ stationary Markov chain (FSMC, obtained from the HMM analysis) is able to simulate SBL regime statistics with sufficient accuracy to be the foundation of a stochastic parameterisation of SBL regimes. We have assessed the performance of the FSMC (using the most likely transition probabilities from HMM analyses) relative to the observed regime statistics (the distributions of event durations and the probability of occurrences of very persistent nights (nights without SBL regime transitions), of any regime transitions, and of multiple subsequent transitions).

The nonstationary occurrence probabilities of very persistent nights as estimated from the HMM analyses cannot be accounted for in a FSMC. The occurrence of regime transitions is slightly overestimated by the FSMC. Transitions subsequent to a preceding ones and the mean event durations in each regime are relatively close to the statistics as estimated with the HMM across all sites and seasons. The recovery time between regime transitions, however, is not explainable by any two-regime FSMC.

By fixing the persistence probability matrix and producing new perturbed HMM regime sequences we have quantified the range of persistence probabilities that are consistent with the most likely HMM regime sequence. At all sites considered, we find that the HMM regime sequence varies only slightly for reasonable variations of transition probabilities.

An analysis of the ranges of persistence probabilities for which a FSMC is consistent with the regime statistics of the HMM analyses indicate that at no tower site considered transition probabilities can be identified which allow a FSMC to match all SBL regime statistics. This result is true even when seasonal non-stationarity is accounted for. The non-Markov behaviour of regime occupation and the fact that aspects of regime transitions such as radiatively-driven turbulence collapse can be simulated by models indicate the need for state-dependent transition probabilities in any explicitly stochastic representation of SBL regime transitions.

With the exception of the sea-based stations state-dependent transition probabilities conditioned on the bulk Richardson number (Ri_B) exhibit a systematic state-dependent behaviour for wSBL to vSBL. Transitions probabilities for turbulence recovery events, on the other hand, demonstrate approximately state-independent characteristics with little consistency across sites. The lack of robustness of the conditional transition probabilities and weak dependence of turbulence recovery on Ri_B imply that Ri_B is not an appropriate conditioning variable.

State-dependent transition probabilities conditioned on stratification, however, demonstrate a systematic state-dependent behaviour for both types of transitions across all stations. The wSBL to vSBL transition probabilities conditioned on the stratification increase almost linearly up to a threshold while the vSBL to wSBL transition probabilities show a sigmoidal behaviour.

A prototype of an explicitly stochastic parameterisation is developed based on the following foundations. The explicitly stochastic parameterisation uses a new local variable S tracking the SBL regime (wSBL or vSBL). At each time step, the occurrence of a wSBL to vSBL transition is determined randomly using the instantaneous state-dependent transition probabilities. If S is determined to be in the vSBL, episodes of enhanced turbulent mixing are added.

Experiments in an idealised single column model (SCM) confirm that such an approach provides a reasonable representation of SBL regime dynamics. The occurrence of vSBL to wSBL transitions is related to the occurrence of turbulence bursts and lags

their occurrence slightly. The simulated responses of temperatures and wind speeds due to the enhanced heat and momentum fluxes towards the surface are comparable to observations. For both transitions, simulated recovery times are consistent with the observed distributions.

We emphasize the fact that the explicitly stochastic parameterisation presented here is only intended to be a proof of concept. The preliminary results suggest that the parameterisation has the potential to simulate SBL regime dynamics in weather and climate models. The observational information on climatological regime statistics, and event duration distributions (cf. AM19b, AM19c, and the present study) can be used in order to tune the presented explicitly stochastic parameterisation to generate the appropriate SBL regime variability. Due to the fact that event duration distributions and stratification-dependent transition probabilities are similar between the midlatitude tower sites we believe that the transition process at those stations can be parameterised independent of the local complexity of the surface conditions (such as surface type, topography etc.). Although at DomeC similar stratification-dependent transition probabilities can be obtained, the altitude range used to determine stratification is different than at the other sites, suggesting that a generalised parameterisation has to take additional local state variables into account. Furthermore, even though a systematic behaviour of transition probabilities conditioned on Ri_B across the different tower sites is absent, Ri_B is a coarse approximation to Ri . Analyses of other data sets (with higher spatial and temporal resolution) allowing for better approximations or an estimation of the gradient Ri or Ri -flux are needed to determine if a systematic behaviour is truly absent.

As our study only considers fixed surface and upper boundary conditions, sensitivity analyses of those in the idealised SCM as well as different resolutions both in time and space must be assessed against different observational case studies. Due to the fact that the first-order closure requires us to consider the effects of intermittent turbulence events as an enhancement of diffusivities for momentum and heat, we have to impose a rather synthetic space time structure of these enhancements. As intermittent turbulence events are associated with the local enhancement of turbulence kinetic energy (TKE), our parameterisation of episodically occurring turbulence bursts can more naturally be implemented in a prognostic TKE scheme as an additional TKE source term (e.g He et al., 2012, 2019). Such an approach would allow the model to determine the space time structure of turbulence pulses as well as the interaction of turbulence bursts. In the future, we will implement the parameterisation in a more complex SCM (with and without a prognostic TKE scheme) to obtain a more comprehensive assessment of its use in numerical weather prediction and climate models.

Finally, the parameterisation requires further information regarding horizontal dependence of regime statistics, as it is not reasonable to expect an entire large-scale weather or climate model grid box to always be in one or the other state. This horizontal dependence will be the subject of a future study. Assessment of the dependence length scales relative to the grid box size will allow the determination of the effects of spatial averaging to the gridbox scale on the probability distribution of SBL quantities.

Appendix A

In this appendix, we present the calculations of quantities based on ‘freely-running’ stationary Markov chains. Note that we introduce in the following equations the notation of $P(i_{t-1} \rightarrow i_t)$ instead of $\mathbf{Q}_{i_t i_{t-1}}$ (cf. equation 2) indicating the regime transition probabilities between two timesteps. Furthermore, we replace the mathematical notation of $i \in \{0, 1\}$ for the regime occupation with the actual terms wSBL and vSBL in order to increase the readability.

A1 Calculation of very persistent regimes

The occurrence probability of very persistent SBL nights in a stationary Markov chain is calculated using the persistence probabilities of the Markov chain (i.e. $P(\text{wSBL} \rightarrow \text{wSBL})$ and $P(\text{vSBL} \rightarrow \text{vSBL})$) as follows

$$Pr(\text{wSBL}|n) = \pi_{\text{wSBL}} P(\text{wSBL} \rightarrow \text{wSBL})^n, \quad (\text{A1})$$

$$10 \quad Pr(\text{vSBL}|n) = \pi_{\text{vSBL}} P(\text{vSBL} \rightarrow \text{vSBL})^n. \quad (\text{A2})$$

where π_{wSBL} and π_{vSBL} are respectively the initial climatological distributions of being in the wSBL or vSBL and n equals the length of the night in hours multiplied by six (corresponding to a data resolution of 10 min)

A2 Calculation of at least one particular SBL transition occurrence

The probability of the occurrence of a particular SBL transition in a night of duration n can be expressed in terms of the probability of the absence of any transitions and the probability of single transitions of the complementary transition. In the case of the wSBL to vSBL transition the single complementary transitions start in the vSBL is only allowed a transition to the wSBL. Naturally, the reverse is true for vSBL to wSBL transitions. That way we account for all possibilities that definitely do not have a transition of the considered type.

The probability of the occurrence of turbulence collapse is:

$$20 \quad Pr((\text{wSBL} \rightarrow \text{vSBL}|n) > 0) = 1 - \underbrace{\pi_{\text{wSBL}} P(\text{wSBL} \rightarrow \text{wSBL})^n}_{\text{prob. of remaining in the wSBL}} - \underbrace{\pi_{\text{vSBL}} P(\text{vSBL} \rightarrow \text{vSBL})^n}_{\text{prob. of remaining in the vSBL}} \quad (\text{A3})$$

$$- \underbrace{\sum_{t=0}^{n-1} \pi_{\text{vSBL}} P(\text{vSBL} \rightarrow \text{vSBL})^t P(\text{vSBL} \rightarrow \text{wSBL}) P(\text{wSBL} \rightarrow \text{wSBL})^{n-t-1}}_{\text{prob. of only vSBL to wSBL transitions, remaining in the wSBL afterwards}}$$

Equivalently, the probability of a turbulence recovery (vSBL to wSBL transition) is given by

$$\begin{aligned}
Pr((vSBL \rightarrow wSBL|n) > 0) &= 1 - \underbrace{\pi_{wSBL} P(wSBL \rightarrow wSBL)^n}_{\text{prob. of remaining in the wSBL}} \\
&\quad - \underbrace{\pi_{vSBL} P(vSBL \rightarrow vSBL)^n}_{\text{prob. of remaining in the vSBL}} \\
&\quad - \underbrace{\sum_{t=0}^{n-1} \pi_{wSBL} P(wSBL \rightarrow wSBL)^t P(wSBL \rightarrow vSBL) P(vSBL \rightarrow vSBL)^{n-t-1}}_{\text{prob. of only wSBL to vSBL transitions, remaining in the vSBL afterwards}}.
\end{aligned} \tag{A4}$$

A3 Calculation of the probability of subsequent turbulence recovery or collapse event occurrences

The probability that a turbulence recovery event occurs after a turbulence collapse in a night of duration n is equal to the sum of the probabilities of all events that include the occurrence of SBL patterns starting at time t_1 in the wSBL, and afterwards showing the sequence $wSBL \rightarrow \overbrace{vSBL \rightarrow \dots \rightarrow vSBL}^{t \times} \rightarrow wSBL$ with no further subsequent recovery events, i.e. the SBL remains in the wSBL or have a maximum of one more collapse. The last part of this calculation assures that no double counting of sequences with length t occur as the probability calculation of being in the wSBL at time t_1 does not include information of the preceding path. The probability of a certain subsequent recovery pattern of length t can then be calculated as

$$\begin{aligned}
Pr((wSBL \rightarrow \overbrace{vSBL \rightarrow \dots \rightarrow vSBL}^{t \times} \rightarrow wSBL|n) > 0) &= \sum_{t_1=0}^{n-t-2} (\pi^T \mathbf{Q}^{t_1})_{wSBL} \\
P(wSBL \rightarrow vSBL) P(vSBL \rightarrow vSBL)^t P(vSBL \rightarrow wSBL) &\left[P(wSBL \rightarrow wSBL)^{n-t-t_1-2} \right. \\
+ \sum_{t_2=0}^{n-t-t_1-3} P(wSBL \rightarrow wSBL)^{t_2} P(wSBL \rightarrow vSBL) P(vSBL \rightarrow vSBL)^{n-t-t_1-t_2-3} &\left. \right],
\end{aligned} \tag{A5}$$

where π is the vector of climatological initial probabilities.

To calculate the overall probability that such a subsequent event occurs is then the summation over all possible t :

$$\begin{aligned}
\sum_t Pr((wSBL \rightarrow \overbrace{vSBL \rightarrow \dots \rightarrow vSBL}^{t \times} \rightarrow wSBL|n) > 0) &= \sum_{t=0}^{n-2} \sum_{t_1=0}^{n-t-2} (\pi^T \mathbf{Q}^{t_1})_{wSBL} \\
P(wSBL \rightarrow vSBL) P(vSBL \rightarrow vSBL)^t P(vSBL \rightarrow wSBL) &\left[P(wSBL \rightarrow wSBL)^{n-t-t_1-2} \right. \\
+ \sum_{t_2=0}^{n-t-t_1-3} P(wSBL \rightarrow wSBL)^{t_2} P(wSBL \rightarrow vSBL) P(vSBL \rightarrow vSBL)^{n-t-t_1-t_2-3} &\left. \right]
\end{aligned} \tag{A6}$$

Equivalently, the probabilities of subsequent turbulence collapses after recovery events are

$$Pr((\text{vSBL} \rightarrow \overbrace{\text{wSBL} \rightarrow \dots \rightarrow \text{wSBL}}^{t \times} \rightarrow \text{vSBL} | n) > 0) = \sum_{t_1=0}^{n-t-2} (\pi^T \mathbf{Q}^{t_1})_{\text{vSBL}}$$

$$P(\text{vSBL} \rightarrow \text{wSBL})P(\text{wSBL} \rightarrow \text{wSBL})^t P(\text{wSBL} \rightarrow \text{vSBL}) \left[P(\text{vSBL} \rightarrow \text{vSBL})^{n-t-t_1-2} \right. \\ \left. + \sum_{t_2=0}^{n-t-t_1-3} P(\text{vSBL} \rightarrow \text{vSBL})^{t_2} P(\text{vSBL} \rightarrow \text{wSBL})P(\text{wSBL} \rightarrow \text{wSBL})^{n-t-t_1-t_2-3} \right] \quad (\text{A7})$$

To calculate the overall probability that such a subsequent event occurs is then the summation over all possible t :

$$\sum_t Pr((\text{vSBL} \rightarrow \overbrace{\text{wSBL} \rightarrow \dots \rightarrow \text{wSBL}}^{t \times} \rightarrow \text{vSBL} | n) > 0) = \sum_{t=0}^{n-2} \sum_{t_1=0}^{n-t-2} (\pi^T \mathbf{Q}^{t_1})_{\text{vSBL}}$$

$$P(\text{vSBL} \rightarrow \text{wSBL})P(\text{wSBL} \rightarrow \text{wSBL})^t P(\text{wSBL} \rightarrow \text{vSBL}) \left[P(\text{vSBL} \rightarrow \text{vSBL})^{n-t-t_1-2} \right. \\ \left. + \sum_{t_2=0}^{n-t-t_1-3} P(\text{vSBL} \rightarrow \text{vSBL})^{t_2} P(\text{vSBL} \rightarrow \text{wSBL})P(\text{wSBL} \rightarrow \text{wSBL})^{n-t-t_1-t_2-3} \right] \quad (\text{A8})$$

5 Appendix B

The idealized SCM is a model of pressure-driven flow in the dry SBL assuming horizontal homogeneity, described in detail in Holdsworth and Monahan (2019). The model equations follow those of Blackadar (1979):

$$\frac{\partial U}{\partial t} = \frac{1}{\rho} \frac{\partial \tau_x}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial x} + f_0 V \quad (\text{B1})$$

$$\frac{\partial V}{\partial t} = \frac{1}{\rho} \frac{\partial \tau_y}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial y} - f_0 U \quad (\text{B2})$$

$$10 \quad \frac{\partial T}{\partial t} = -\frac{1}{\rho c_p} \frac{\partial H}{\partial z} - C_{HL} \quad (\text{B3})$$

$$\frac{\partial T_s}{\partial t} = C_1(I_{lw} - \sigma T_s^4 - H_0) - C_2(T_s - T_d) \quad (\text{B4})$$

where the three state variables $U(z, t)$, $V(z, t)$ and $T(z, t)$ are the zonal velocity, meridional velocity, and potential temperature.

The surface temperature T_s is determined by the sum of radiative, turbulent sensible heat, and surface heat fluxes as described in more detail below. The constant $C_{HL} = 2 \text{ K h}^{-1}$ represents the atmospheric cooling due to net long-wave radiative flux

15 divergence and is set as a fixed constant for simplicity.

The geostrophic wind components are defined by

$$U_g = -\frac{1}{f_0 \rho} \frac{\partial p}{\partial y}, \quad (\text{B5})$$

$$V_g = \frac{1}{f_0 \rho} \frac{\partial p}{\partial x}, \quad (\text{B6})$$

with the magnitude of the geostrophic wind speed given by $S_g = (U_g^2 + V_g^2)^{0.5}$.

The vertical heat flux $H = \rho c_p \overline{w'T'}$ and shear stresses $\tau_x = -\rho \overline{U'w'}$ and $\tau_y = -\rho \overline{V'w'}$ (where w is the vertical velocity) are parameterized using first order closure $\tau_x/\rho = K_m \partial_z U$, $\tau_y/\rho = K_m \partial_z V$ and $H/\rho c_p = -K_H \partial_z T$, where K_m and K_h are the diffusivities for respectively momentum and heat. The diffusivities are taken to be the sum of molecular and turbulent contributions (Moene et al., 2010):

$$K_m = l^2 |\partial_z U| f_m(\text{Ri}) + \nu \quad (\text{B7})$$

$$K_h = l^2 |\partial_z U| f_h(\text{Ri}) + \lambda \quad (\text{B8})$$

where the molecular contribution $\nu = 1.5 \times 10^{-5} \text{ m}^2 \text{ s}^{-1}$ is the kinematic viscosity. The molecular Prandtl number is fixed at $\text{Pr} = 0.72$ and $\lambda = \nu/\text{Pr}$ is the molecular diffusivity. The mixing length is given by

$$l = \left(1 - \exp\left(-\frac{u_* z}{C\nu}\right)\right) \left(\frac{\kappa(z - z_0)}{(1 + \kappa(z - z_0)/\lambda_0)}\right) \quad (\text{B9})$$

with κ the von Kármán constant, u_* friction velocity, $C = 26$ (Van Driest, 1951), and $\lambda_0 = 0.00027 S_g / f_0$ (Blackadar, 1962).

The stability functions $f_{m,h}(\text{Ri})$, depend on the Richardson number $\text{Ri} = \frac{g}{T_{\text{REF}}} \frac{\partial_z T}{(\partial_z U)^2}$ which are related to the similarity functions from MOST $\phi_{m,h}(\zeta)$ by

$$f_m(\text{Ri}_{eq}) = \phi_m^{-2}(\zeta) \quad (\text{B10})$$

$$f_h(\text{Ri}_{eq}) = \phi_m^{-1}(\zeta) \phi_h^{-1}(\zeta)$$

where $\zeta = z/L$ is the stability parameter and $L = -\frac{u_*^2}{\kappa \frac{g}{T_s} \frac{H_0}{c_p \rho}}$ is the Obukhov length. In our simulations, we use the Businger-Dyer formulation given by $\phi_{m,h}(\zeta) = 1 + \beta\zeta$ where $\beta = 1/\text{Ri}_c = 5.2$ (Businger, 1988).

At the upper boundary of the model we impose the boundary condition that the flow is geostrophic and a no-flux condition so $H = 0$ and $\tau = 0$. The lower boundary of the model domain is determined by the roughness length (assumed to be the same for momentum and energy) with no-slip boundary conditions $U(z_0) = 0$ and $T(z_0, t) = T_s(t)$.

The model implements the surface energy scheme of Blackadar (1976), known as the force-restore method. The surface, represented as an infinitesimally thin layer with temperature $T_s(t)$ at $z = z_0$, is forced by the net radiation and sensible heat flux and restored to the subsurface temperature through the subsurface energy fluxes. The damping depth of the diurnal forcing $d = (2\lambda_s/C_s\omega)^{0.5}$, where $C_s = \rho_s c_s$ is the volumetric heat capacity, is associated with a sinusoidal diurnal forcing. The temperature at this depth is set as the subsurface temperature $T_d = 281 \text{ K}$. In Eq. (B4), $C_1 = 2/(0.95C_s d)$ and $C_2 = 1.18(2\pi/T_d)$. The first two terms in Eq. (B4) constitute the net long-wave radiation Q_n , the third term is the sensible heat flux into the atmosphere due to turbulent transports H_0 , and the fourth term is the heat flux into the subsurface G . As our focus is on the stably stratified boundary layer we do not include the effects of albedo or latent heat in the heat budget. We also neglect the effects of the vegetation canopy.

The downwelling longwave radiation is given by

$$I_{lw} = \sigma(Q_c + 0.67(1 - Q_c)(1670Q_a)^{0.08})T_a^4 \quad (\text{B11})$$

where Q_c is the cloud fraction, Q_a is the specific humidity and T_a is the atmospheric temperature at a reference level z_a just above the Earth surface (Staley and Jurica, 1972; Deardorff, 1978). For simplicity, Q_a is held constant at 0.003 kg kg^{-1} .

The equations are integrated in time using a fourth order Runge-Kutte method. The spatial discretization is obtained using finite differences on a logarithmic grid. This grid has 50 vertical levels with a much finer resolution in the boundary layer than aloft and is determined by $z_j = \Delta z_0 \frac{r^j - 1}{r - 1}$ with a stretch factor $r = \frac{\Delta z_j}{\Delta z_{j-1}} \simeq 1.10$ and an initial step size of $\Delta z_0 = 2 \text{ m}$. The prognostic variables U, V , and T are defined at the z_i grid levels, while the diagnostic variables of H , τ , and Ri are defined on $z_{i+\frac{1}{2}}$ levels.

We define $t = 0$ as the time when the shortwave radiation goes to zero acknowledging the fact that observations indicate that the onset of the SBL can occur before this time (van Hooijdonk et al., 2017; van de Wiel et al., 2017, AM19a). The initial conditions were set in accordance with the logarithmic equations that arise from MOST. The near-neutral profiles for temperature and wind used to initialize the model are given by

$$\begin{aligned} U_0 &= \frac{U_{\text{ext}}}{\kappa} \ln(z/z_0) \\ V_0 &= \frac{V_{\text{ext}}}{\kappa} \ln(z/z_0) \\ T_0 &= T_s + \frac{\theta_{\text{ext}}}{\kappa} \ln(z/z_0) \end{aligned} \tag{B12}$$

where $U_{\text{ext}} = U_g \kappa / \ln(h/z_0)$, $V_{\text{ext}} = V_g \kappa / \ln(h/z_0)$ and $\theta_{\text{ext}} = 0.01 \text{ K}$ (Monin and Obukhov, 1954). For simplicity, we set $\frac{\partial p}{\partial y} = 0$ in all of our simulations, so U_0 is identically zero at the start of the simulation.

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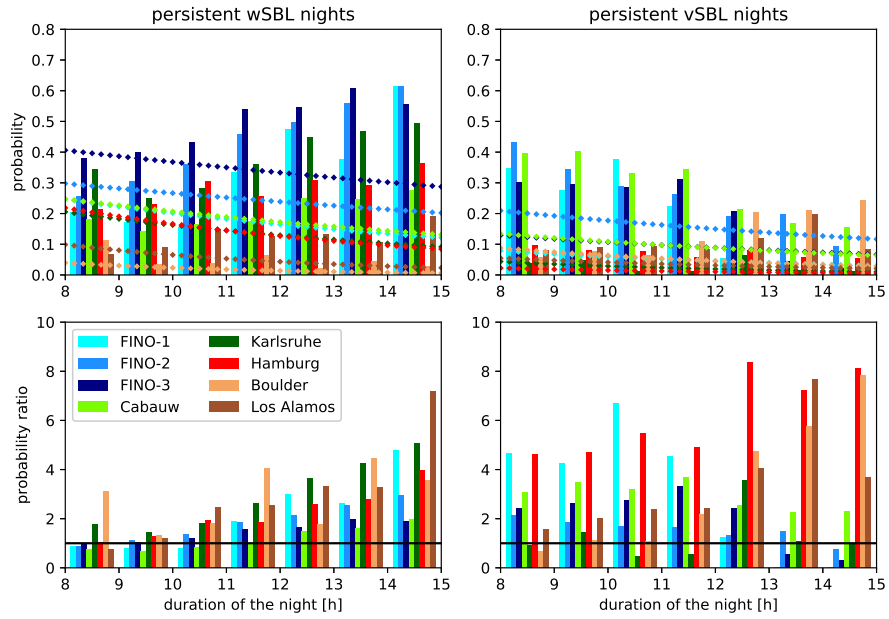


Figure 11. Occurrence probabilities of very persistent wSBL (upper left panel, bars) and vSBL (upper right panel, bars) as estimated from the VP_{ref} for nights of different lengths (in one hour increments) at the different tower sites compared to the occurrence probabilities of very persistent nights computed from the FSMC using Q_{ref} (diamonds). Lower panels show the ratio of the probabilities in the upper panels (values from the VP_{ref} divided by those from the FSMC).

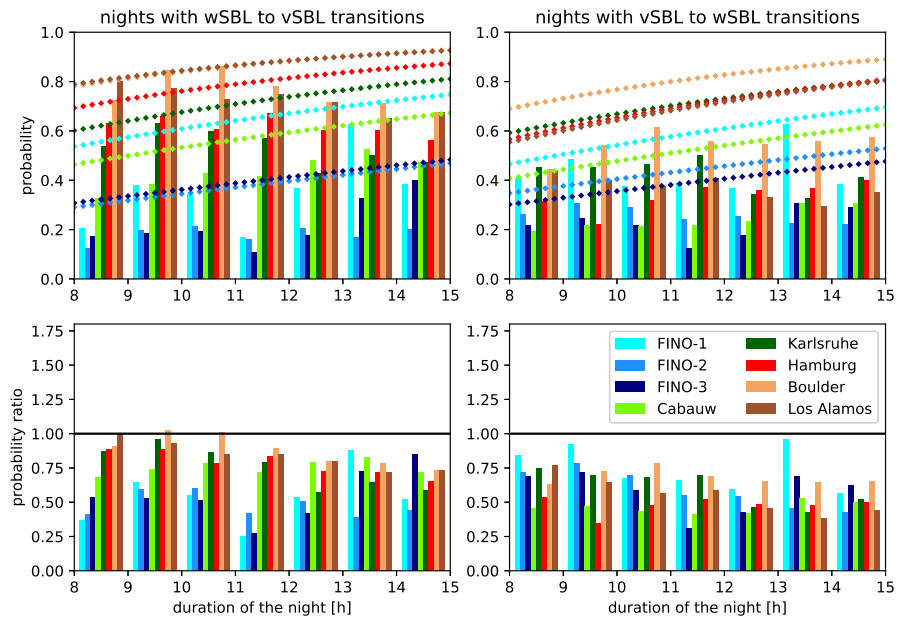


Figure 12. As in Figure 11 but for the occurrence probabilities of **at least one wSBL to vSBL (left panels) or vSBL and wSBL (right panels) transition within in a night.**

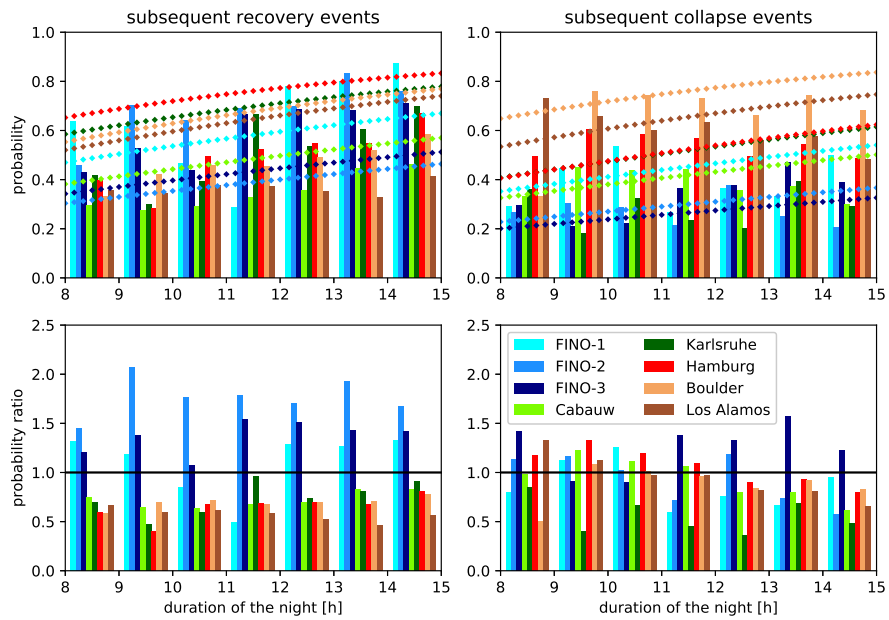


Figure 13. As in Figure 11, but for the probabilities of the occurrence of turbulence recovery events subsequent to turbulence collapse (left panels) and turbulence collapse events subsequent to turbulence recovery events (right panels).

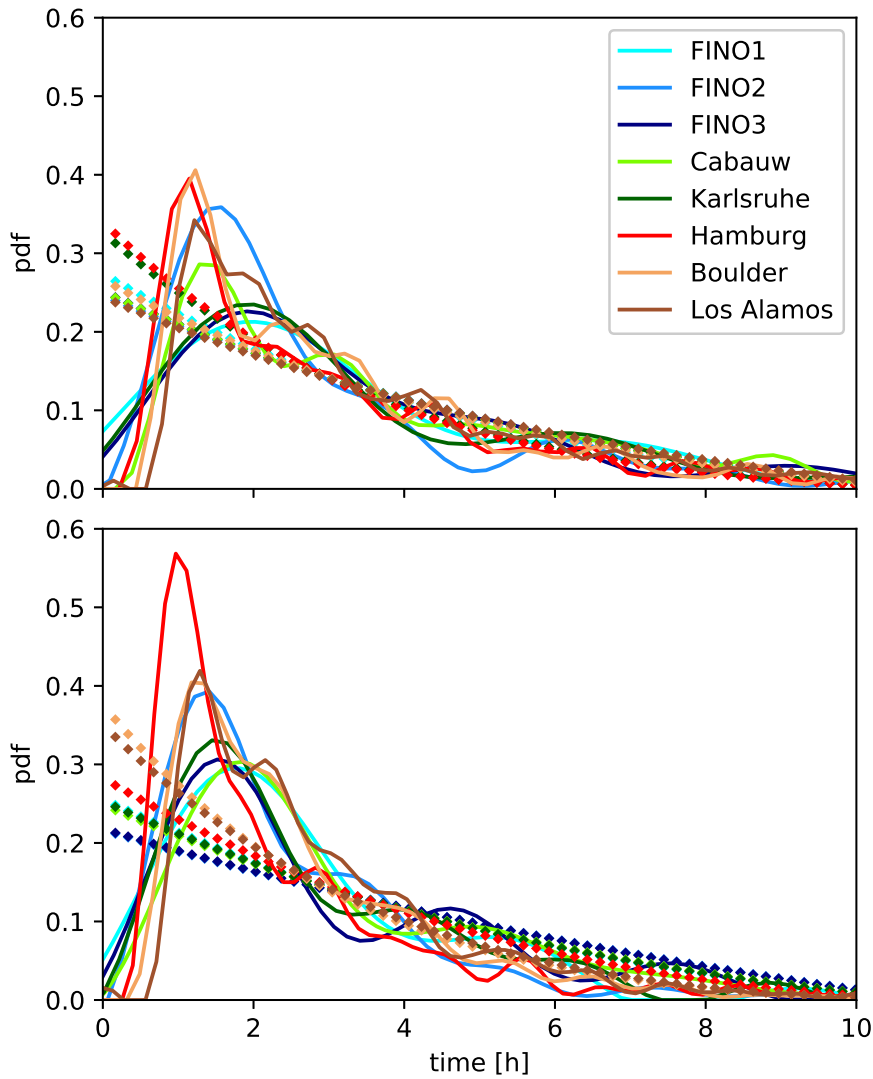


Figure 14. Probability density functions of the vSBL (top) and wSBL event durations (bottom) as estimated from the VP_{ref} (solid lines) at the different tower sites compared to FSMC pdfs computed using Q_{ref} and a nighttime duration of 12 hours (diamonds). All pdfs are calculated with the multivariate kernel density estimation by O'Brien et al. (2014, 2016).

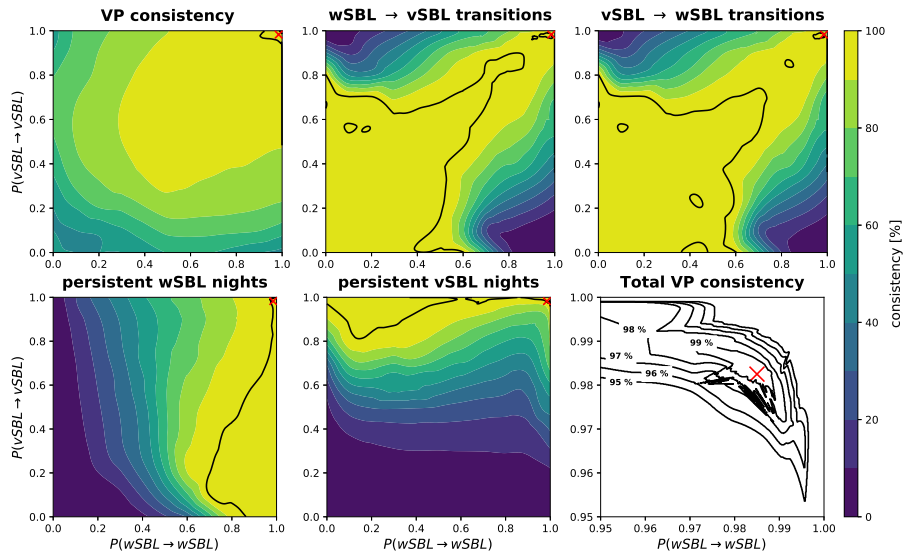


Figure 15. Consistency of reference and perturbed regime occupation statistics as functions of Markov chain persistence probabilities. Displayed are: the **occupation** consistency of the VP (upper left), the consistency of wSBL to vSBL (upper middle) and vSBL to wSBL (upper right) transitions in the VP, the consistency of the occurrence of **very** persistent wSBL (lower left) and vSBL (lower middle) nights. The 99 % consistency values in each VP characteristic is delineated by a black line. Isolines of the total consistency of the perturbed and reference VP (ranges of persistence probabilities where all SBL regime statistics considered have the same or higher consistencies with VP_{ref}) are illustrated in the bottom right panel. In each panel the reference value at Cabauw is shown by a red cross.

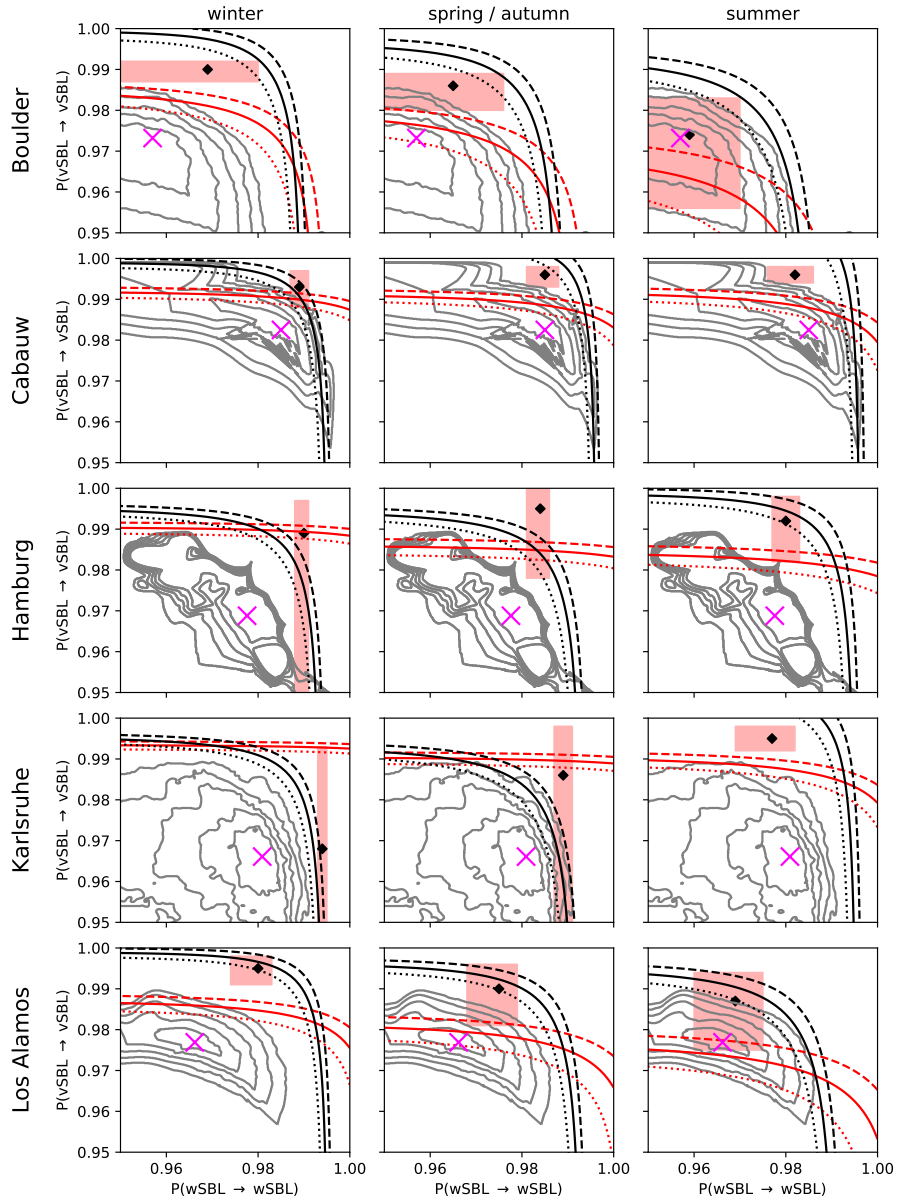


Figure 16. Values of persistence probabilities for which the occurrence probability of at least one wSBL to vSBL transition (turbulence collapse) in a night (red lines) or one vSBL to wSBL (turbulence recovery) in a night (black lines) as computed from a stationary Markov chain equal the observed values. Solid, dashed, and dotted lines correspond respectively the observed values, a probability 5 % below the observed values and a probability 5 % above the observed values. The ranges of persistence probabilities where the occurrence probability of very persistent nights in a stationary Markov chain agrees with observations in a $\pm 5\%$ uncertainty band is depicted by the red rectangle with a diamond displaying the values for the exact observational probability occurrence of persistent nights. The persistence probabilities values corresponding to 95 to 99 % total consistency of the perturbed VP with VP_{ref} in the HMM analysis are depicted in grey contours. The persistence probabilities corresponding to Q_{ref} value are marked by a pink cross.

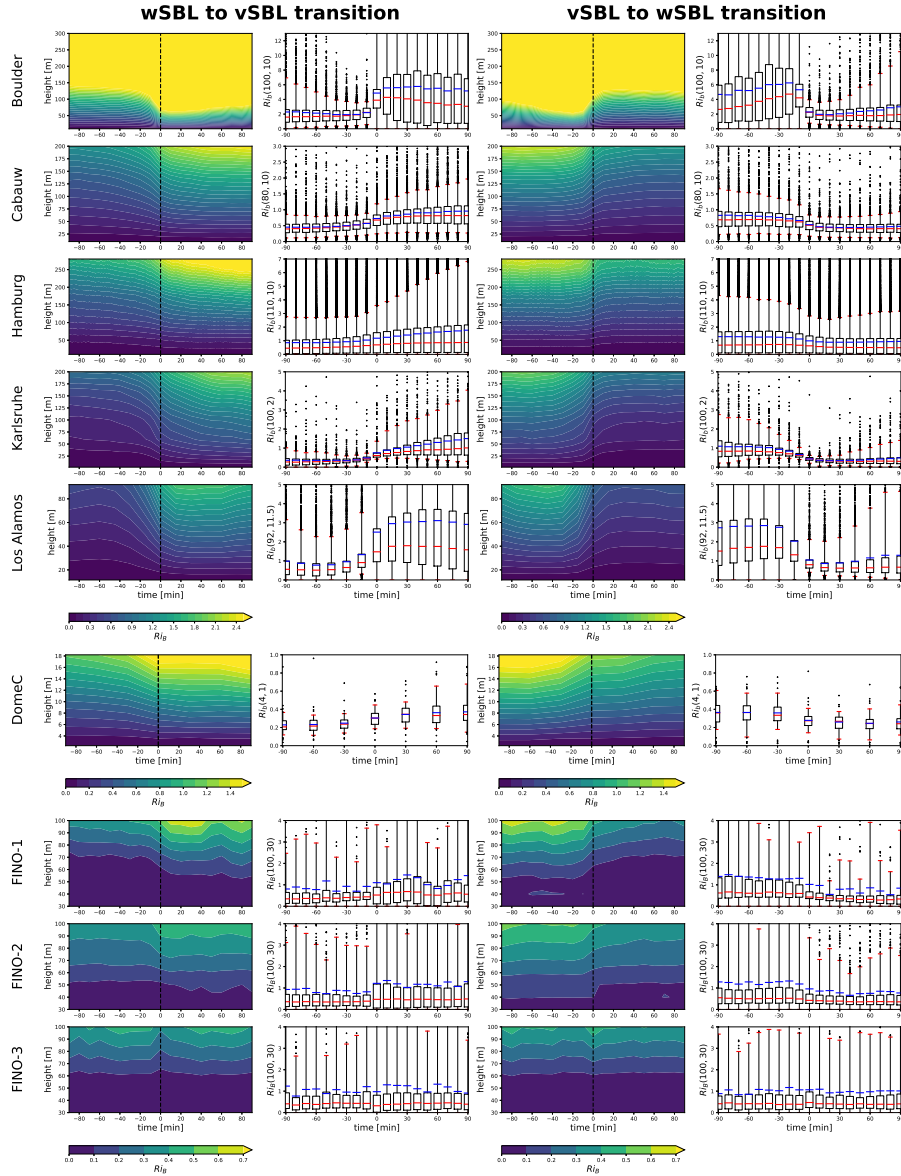


Figure 17. Time evolution of the composite median of the bulk Richardson number (Ri_B ; as determined between each observational level and about 10 m, 1 m, and 30 m for respectively the land-, glacial-, and sea-based tower stations) at the different tower sites in times of turbulence collapse (wSBL to vSBL transition; first and second columns) and turbulence recovery events (vSBL to wSBL transition; third and fourth columns) as determined by the HMM analyses. The composites show the 90 minutes before and after the transitions at time 0 (dashed reference line). Second and fourth row: The distribution of the Ri_B showing the interquartile range (box), 5th to 95th percentile range (outer red bars), median, and mean values (respectively red and blue lines).

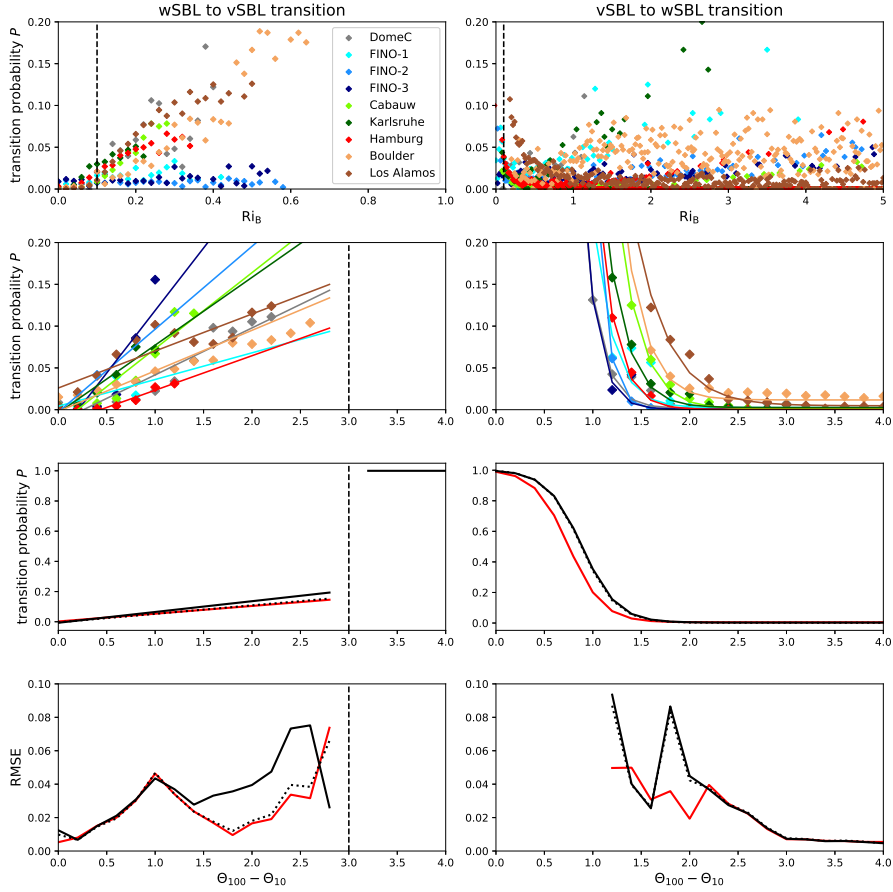


Figure 18. First row: Probabilities for wSBL to vSBL (left) and vSBL to wSBL transitions (right) conditioned on the bulk Richardson number (binned by 0.02 increments; coloured diamonds). Second row: Transition probabilities conditioned on the stratification ($\Theta_{100} - \Theta_s$ with the exception $\Theta_4 - \Theta_s$ for DomeC; binned by 0.2 K increments) and best-fit curves. In order to reduce sampling variability in those panels, only data are considered for which the regime occupation probability in a bin exceeds 0.1 % of all data within that regime. Third row: Parameterisation of the state-dependent transition probabilities conditioned on stratification using the mean and median parameter sets of the curve fits (respectively solid and dotted black lines). The best-fit estimated through all stratification data is displayed in red. Fourth row: Root mean square error (RMSE) between the conditional transition probabilities as estimated from HMM analyses and the parameterised conditional transition probabilities. All transition probabilities have been normalised to 10 minute intervals.

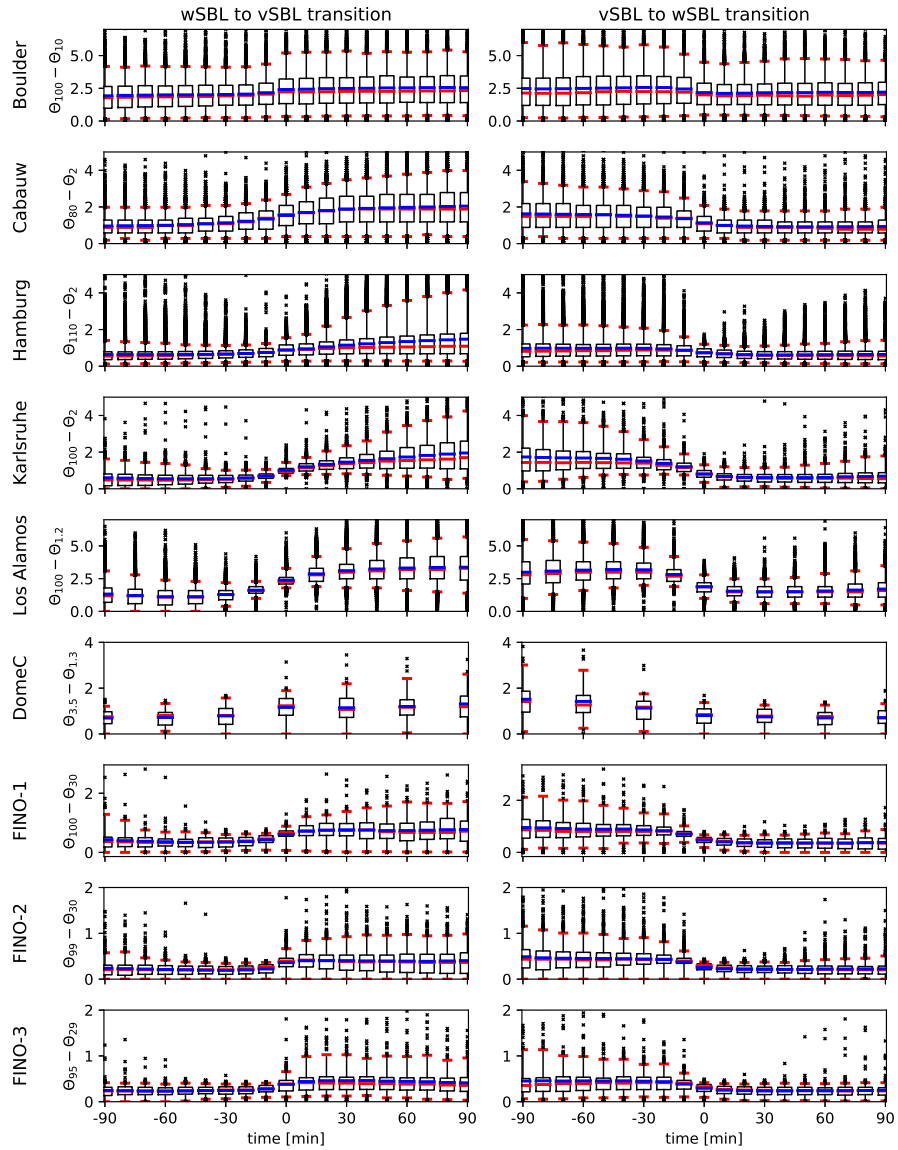


Figure 19. Time evolution of the distribution of the stratification as estimated by the potential temperature difference between about 100 m and observations closest to the surface for land-based stations, between about 4 m and 1 m for DomeC, and between about 100 m and 30 m for the sea-based stations in times of wSBL to vSBL (left) and vSBL to wSBL transitions (right). The distributions show the interquartile range (box), 5th to 95th percentile range (outer red bars), median, and mean values (respectively red and blue lines).

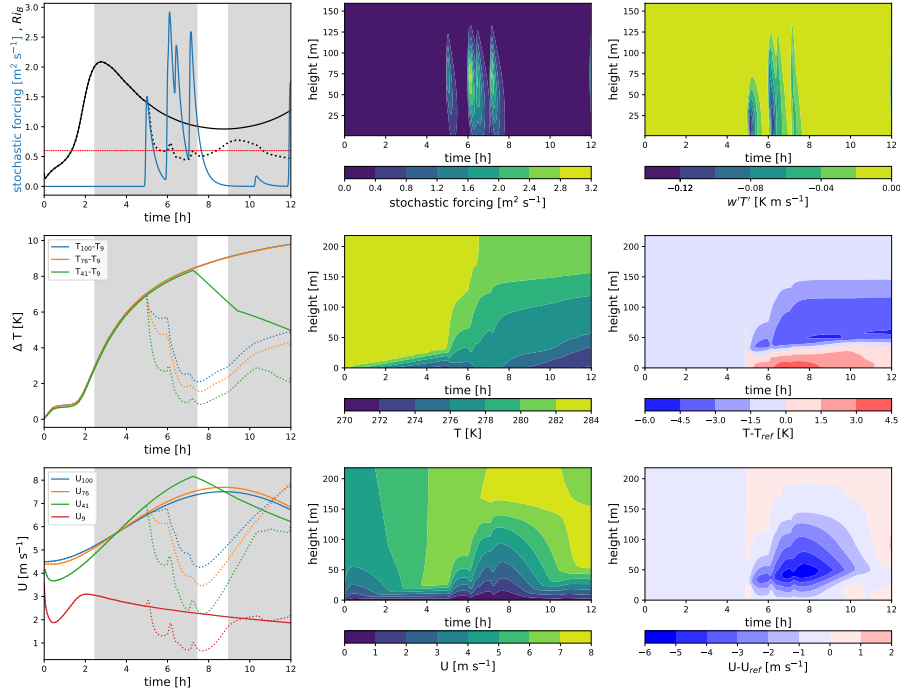


Figure 110. One realisation of a twelve hour simulation of the evolution of the nocturnal boundary layer (with time zero being the time the net energy surface flux becomes negative) using the proposed parameterisation. Times when S is in the vSBL are highlighted in grey. Top row from left to right: Ri_B (solid and dotted black lines respectively for the reference experiment without the stochastic parameterisation and the experiment with the stochastic parameterisation) and the strength of the stochastic forcing (blue line; left); the structure of the stochastic forcing function (middle), and the resulting heat fluxes (right). Middle row from left to right: the stratification between different levels (left), the temperature profiles (middle), and the difference in the temperature field to the reference experiment without the stochastic parameterisation (right). Third row from left to right: Wind speeds at different heights (left), wind speed profiles (middle) and the difference in the wind field to the reference experiment without the stochastic parameterisation (right).

Table 11. Basic information about the different land-, **glacial-**, and **sea-**based tower sites (geographical coordinates, time resolution) and their individual reference HMM state variable inputs \mathbf{Y} (wind speeds W_h and static stabilities $\Delta\Theta$ with their observational levels h) and reference transition probability matrices (\mathbf{Q}_{ref}) of HMM analyses estimated from \mathbf{Y} . Starting regimes for the transition probability matrices are denoted with a star. Transition probability matrices at Hamburg, Los Alamos, and **DomeC** are transformed to a 10 minute time resolution, so a direct comparison to other sites is possible. To retrieve original transition probability matrices at these sites the **1/10**, **3/2**, and **3** matrix powers (respectively) must be taken.

Tower site	Reference state variables	\mathbf{Q}_{ref}	References
<i>Land-based tower sites</i>			
<i>Boulder</i> 40.0500 N, 105.0038 W, 1584 m 2008–2015 (10 minute)	$\mathbf{Y} = (W_{100} - W_{10},$ $0.5(W_{100} + W_{10}),$ $\Theta_{100} - \Theta_{10})$	$wSBL$ $vSBL$ $wSBL^*$ 0.9570 0.0430 $vSBL^*$ 0.0268 0.9732	Kaimal and Gaynor (1983), Blumen (1984)
<i>Cabauw</i> 51.9700 N, 4.9262 E, -0.7 m 2001–2015 (10 minute)	$\mathbf{Y} = (W_{200} - W_{10},)$ $0.5(W_{200} + W_{10}),$ $\Theta_{200} - \Theta_2)$	$wSBL$ $vSBL$ $wSBL^*$ 0.9850 0.0150 $vSBL^*$ 0.0175 0.9825	Ulden and Wieringa (1996)
<i>Hamburg</i> 53.5192 N, 10.1051 E, 0.3 m 2005–2015 (1 minute)	$\mathbf{Y} = (W_{250} - W_{10},$ $0.5(W_{250} + W_{10}),$ $\Theta_{250} - \Theta_2)$	$wSBL$ $vSBL$ $wSBL^*$ 0.9776 0.0224 $vSBL^*$ 0.0312 0.9688	Brümmer et al. (2012), Floors et al. (2014), Gryning et al. (2016)
<i>Karlsruhe</i> 49.0925 N, 8.4258 E, 110.4 m 2003–2013 (10 minute)	$\mathbf{Y} = (W_{200} - W_2,$ $0.5(W_{200} + W_2),$ $\Theta_{200} - \Theta_2)$	$wSBL$ $vSBL$ $wSBL^*$ 0.9809 0.0191 $vSBL^*$ 0.0339 0.9661	Kalthoff and Vogel (1992), Wenzel et al. (1997), Barthlott et al. (2003)
<i>Los Alamos</i> 35.8614 N, 106.3196 W, 2263 m 1995–2015 (15 minute)	$\mathbf{Y} = (W_{92} - W_{11.5},$ $0.5(W_{92} + W_{11.5}),$ $\Theta_{92} - \Theta_{1.2})$	$wSBL$ $vSBL$ $wSBL^*$ 0.9662 0.0338 $vSBL^*$ 0.0231 0.9769	Bowen et al. (2000), Rishel et al. (2003)
<i>Glacial-based tower sites</i>			
<i>DomeC</i> 75.1000 S, 123.3000 E, 3233 m 2011–2016 (30 minute)	$\mathbf{Y} = (W_9 - W_{1.3},$ $0.5(W_9 + W_{1.3}),$ $\Theta_9 - \Theta_{1.3})$	$wSBL$ $vSBL$ $wSBL^*$ 0.9916 0.0084 $vSBL^*$ 0.0076 0.9924	Genthon et al. (2010, 2013), Vignon et al. (2017a, b)
<i>Sea-based tower sites</i>			
<i>FINO-1</i> 54.0140 N, 6.5876 E, 0 m 2004–2015 (10 minute)	$\mathbf{Y} = (W_{100} - W_{33},$ $0.5(W_{100} + W_{33}),$ $\Theta_{100} - \Theta_{30})$	$wSBL$ $vSBL$ $wSBL^*$ 0.9833 0.0167 $vSBL^*$ 0.0232 0.9768	Beeken et al. (2008), Fischer et al. (2012)
<i>FINO-2</i> 55.0069 N, 13.1542 E, 0 m 2008–2015 (10 minute)	$\mathbf{Y} = (W_{102} - W_{32},$ $0.5(W_{102} + W_{33}),$ $\Theta_{99} - \Theta_{30})$	$wSBL$ $vSBL$ $wSBL^*$ 0.9908 0.0092 $vSBL^*$ 0.0138 0.9862	Dörenkämper et al. (2015)
<i>FINO-3</i> 55.1950 N, 7.1583 E, 0 m 2010–2015	$\mathbf{Y} = (W_{100} - W_{30},$ $0.5(W_{100} + W_{30}),$ $\Theta_{95} - \Theta_{29})$	$wSBL$ $vSBL$ $wSBL^*$ 0.9918 0.0082 $vSBL^*$ 0.0157 0.9843	Fischer et al. (2012)

Table 12. Nighttime durations (d) for the different seasons for estimations of regime statistics from the VP_{ref} and corresponding average durations for calculations in a FSMC.

Season	VP_{ref} [h]	FSMC [h]
winter	$13 \leq d$	14
spring / autumn	$11 \leq d \leq 13$	12
summer	$d \leq 11$	10

Table 13. Probabilities of the occurrence **probabilities of at least one** wSBL to vSBL or vSBL to wSBL transitions in a night, of the occurrence **probabilities** of very persistent wSBL or vSBL nights, and of the climatological initial distributions of starting a night in the wSBL or vSBL (respectively π_{wSBL} and π_{vSBL}) at the different tower sites for different seasons **as estimated from the VP_{ref}**.

Tower station	season	Observations					
		Transitions		Very persistent		clim.	
		wSBL to vSBL [%]	vSBL to wSBL [%]	wSBL nights [%]	vSBL nights [%]	π_{wSBL} [%]	π_{vSBL} [%]
Land-based stations							
Boulder	winter	68.95	56.5	3.22	22.94	45.59	54.41
	spring / autumn	74.84	55.18	4.44	15.43	56.24	43.76
	summer	82.07	54.41	5.32	7.29	65.2	34.8
Cabauw	winter	48.03	31.69	29.22	14.87	73.44	26.56
	spring / autumn	44.75	22.37	21.36	27.68	63.16	36.84
	summer	35.99	19.1	16.49	38.92	50.50	49.50
Hamburg	winter	54.58	38.78	37.25	5.01	87.36	12.64
	spring / autumn	63.16	36.26	28.36	7.02	89.77	10.23
	summer	59.94	22.86	24.89	10.81	82.22	17.78
Karlsruhe	winter	38.41	31.49	58.13	0.69	95.85	4.15
	spring / autumn	49.45	41.76	40.66	3.85	89.56	10.44
	summer	40.96	22.5	13.85	32.18	57.23	42.77
Los Alamos	winter	65.16	30.95	13.24	16.88	74.41	25.59
	spring / autumn	72.99	36.92	12.86	10.13	79.46	20.54
	summer	74.32	38.57	11.73	9.58	78.75	21.25
Ocean-based stations							
FINO-1	winter	37.84	37.84	62.16	0.00	91.89	8.11
	spring / autumn	23.64	38.18	38.18	16.36	52.73	47.27
	summer	13.64	18.73	56.73	16.91	67.64	32.36
FINO-2	winter	18.93	23.33	58.89	12.81	75.72	24.28
	spring / autumn	18.12	24.83	47.65	22.82	64.77	35.23
	summer	15.1	26.72	28.2	40.19	39.75	60.25
FINO-3	winter	31.56	29.51	57.38	6.97	86.48	13.52
	spring / autumn	14.08	14.79	54.23	26.06	66.2	33.80
	summer	12.23	14.61	50.32	27.16	61.36	38.64

Table 14. Parameter values for the state-dependent parametric probability transition functions conditioned on stratification $\Theta_{100} - \Theta_s$ ($\Theta_4 - \Theta_s$ at DomeC) at the different tower locations and the RMSE between parameterised values and those obtained from estimations of HMM analyses. The mean and median values of the parameters are stated below together with the best fit approximation through all data (averaged).

Tower station	Parameters $P(\text{wSBL} \rightarrow \text{vSBL} \Theta_{100} - \Theta_s)$			Parameters $P(\text{vSBL} \rightarrow \text{wSBL} \Theta_{100} - \Theta_s)$				
	α	β	RMSE	α	β	γ	δ	RMSE
Boulder	0.0484	-0.0020	0.0257	-0.4953	1.060	0.4023	0.5069	0.0061
Cabauw	0.0909	-0.0179	0.0171	-0.5012	1.0022	0.4164	0.5023	0.0025
DomeC	0.0562	-0.0146	0.0144	-0.5009	0.7213	0.2990	0.5027	0.0055
FINO-1	0.0319	0.0042	0.0099	-0.5017	0.7736	0.3607	0.5042	0.0116
FINO-2	0.0991	-0.0028	0.0067	-0.5000	0.9080	0.2140	0.5001	0.0002
FINO-3	0.1495	-0.0308	0.0278	-0.5001	0.7513	0.2638	0.5007	0.0250
Hamburg	0.0413	-0.0180	0.0084	-0.5010	0.8624	0.3284	0.5013	0.0019
Karlsruhe	0.0811	-0.0039	0.0084	-0.5010	0.8811	0.3896	0.5036	0.0048
Los Alamos	0.0443	0.0260	0.0164	-0.4985	1.0290	0.6089	0.5032	0.0073
mean	0.0714	-0.0066		-0.5000	0.8877	0.3648	0.5028	
median	0.0562	-0.0039		-0.5009	0.8811	0.3607	0.5027	
averaged	0.0513	0.0020		-0.4997	0.7505	0.3540	0.5045	

Table 15. Values for the free parameters in the stochastic forcing parameterisation as used in all SCM experiments

Parameter	symbol	value
occurrence rate of turbulence pulses	λ_{SF}	5 % per 10 min
maximal possible strength of turbulent ‘kick’	R	$3 \text{ m}^2 \text{ s}^{-1}$
growth time	τ_w	600 s
eddy overturning timescale	τ_e	1200 s
centre of turbulent ‘kick’ at t_0	h_b	75 m
centre of turbulent ‘kick’ at the end	h_e	20 m
vertical migration timescale of centre	τ_h	900 s
width of turbulent ‘kick’ at t_w	σ_w	30 m
width of turbulent ‘kick’ at the end	σ_e	50 m
broadening timescale	τ_σ	900 s