1	An improved ARIMA model for precipitation simulations
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12 Abstract

13 Auto Regressive Integrated Moving Average (ARIMA) models have been widely used to 14 calculate monthly time series data formed by inter-annual variations of monthly data or inter-monthly 15 variation. However, the influence brought about by inter-monthly variations within each year is often 16 ignored. An improved ARIMA model is developed in this study accounting for both the inter-annual and inter-monthly variation. In the present approach, clustering analysis is performed first to 17 18 hydrologic variable time series. The characteristics of each class are then extracted and the correlation 19 between the hydrologic variable quantity to be predicted and characteristic quantities constructed by 20 linear regression analysis. ARIMA models are built for predicting these characteristics of each class 21 and the hydrologic variable monthly values of year of interest are finally predicted using the modeled 22 values of corresponding characteristics from ARIMA model and the linear regression model. A case 23 study is conducted to predict the monthly precipitation in Lanzhou precipitation station, China, using 24 the model, and the results show that the accuracy of the improved model is significantly higher than 25 the seasonal model, with the mean residual achieving 9.41 mm and the forecast accuracy increasing 26 by 21%.

Keywords Hydrological Process, Seasonal ARIMA model, Clustering Regression, Precipitation
 prediction

30 1. Introduction

31 Hydrological processes are complicated; they are influenced by not only deterministic, but also 32 stochastic factors (Wang et al. 2007). The deterministic change in a hydrological process is always 33 accompanied by the stochastic change. Generally speaking, determinism includes periodicity, 34 tendency, and abrupt change. A strict deterministic hydrological process is rare. Stationary time series has been widely used in hydrological data assimilation and prediction to tackle the stochastic factors 35 in hydrological processes. From the point of view of stochastic processes, hydrological data series 36 37 usually comprises trend term and stationary term. The basic idea of Auto Regressive Integrated 38 Moving Average (ARIMA) model, one of the most commonly used time series model, is to remove 39 the trend term of series by difference elimination, so that a nonstationary series can be transformed 40 into a stationary one. Some researchers have used ARIMA model for the analysis of hydrological 41 process without considering the effects of seasonal factors (Jin et al. 1999; Niua et al. 1998; Toth et al. 42 1999). However, most studies (Ahmad et al. 2001; Lehmann et al. 2001; Qi et al. 2006) neglected 43 stationary test and the influence from inter-monthly variation within a year. In this paper, the seasonal 44 ARIMA model is improved by removing the effect of seasonal factors, and the improved model is 45 tested through a case study. The paper is organized as follows: the ARIMA model is introduced first, followed by the introduction of the issues in the currently existing ARIMA model and our proposed 46 47 methods to improve it. A case study is conducted and discussion is addressed finally.

48 **2. ARIMA model**

49 A hydrological time series $\{y_t, t=1,2,\dots,n\}$ could be either stationary or nonstationary. Given 50 that there are essentially no strictly deterministic hydrological processes in nature, the analysis of 51 hydrological data by means of nonstationary time series is of importance, among which ARIMA 52 model is one of the available choices.

53 2.1 ARIMA model

54

For a stationary time series, ARMA(p,q) model is defined as follows:

55 $y_{t} = \phi_{1}y_{t-1} + \phi_{2}y_{t-2} + \dots + \phi_{p}y_{t-p} + u_{t} - \theta_{1}u_{t-1} - \theta_{2}u_{t-2} - \dots - \theta_{q}u_{t-q}$ (1)

56 Where *p* denotes the autoregressive (AR) parameters, *q* represents the moving average (MA) 57 parameters, the real parameters ϕ_1, ϕ_2, \cdots , and ϕ_p are called autoregressive coefficients, the real 58 parameters θ_j (j = 1, 2, ..., q) are moving average coefficients, and u_t is an independent white 59 noise sequence, i.e. $u_t \sim N(0, \sigma^2)$. Usually the mean of $\{y_t\}$ is zero; if not, $y'_t = y_t - \mu$ is used in 50 the model.

61 Lag operator (B) is then introduced, thus

62
$$\varphi(B) = 1 - \varphi_1 B - \varphi_2 B^2 - \dots - \varphi_p B^p$$
(2)

63
$$\theta(B) = 1 - \theta_1 B - \theta_2 B^2 - \dots - \theta_q B^q$$
(3)

64 where $\varphi(B)$ is the autoregressive operator and $\theta(B)$ is the moving-average operator.

65 Then the model can be simplified as

$$\phi(B)y_t = \phi(B)u_t \tag{4}$$

67 If $\{y_t\}$ are nonstationary, we can obtain the stationarized sequence z_t by means of difference, i.e.,

$$z_t = (1-B)^d y_t = \nabla^d y_t \tag{5}$$

69 where *d* is the number of regular differencing. Then the corresponding ARIMA (p, d, q) model for 70 y_t can be built (Box et al. 1997), where *d* is the number of differencing passes by which the 71 nonstationary time series might be described as a stationary ARMA process.

72 **2.2 Seasonal** ARIMA(p,d,q) model

Most hydrological time series have obviously seasonal (quasi-periodic) variation (Box et al. 1967), representing recurring of hydrological processes over a relatively (but not strictly) fixed time interval. Monthly data series often shows a seasonal period of 12 months while quarterly data series always present a period of 4 quarters. Seasonality can be determined by examining whether the autocorrelation function of the data series with a specified seasonal order is significantly different from zero. For instance, if the autocorrelation coefficient of a monthly data series with new data series formed by a lag of 12 months is not significantly different from 0, the monthly data series does not have a seasonality of 12 months; if the autocorrelation coefficient is significantly different from 0, it is very likely this monthly data series has a seasonality of 12 months. A seasonal ARIMA model can be built for a data series with seasonality.

For a time series $\{y_t\}$, its seasonality can be eliminated after *D* orders of differencing with a period of *S*. If a further *d* orders of regular differencing is still needed in order to make the data series stationary, a seasonal ARIMA can be built for the data series as follows,

$$\phi_{p}(B)\Phi_{p}(B^{s})(1-B)^{d}(1-B^{s})^{D}y_{t} = \theta_{a}(B)\Theta_{0}(B^{s})u_{t}$$
(6)

where P is the number of seasonal autoregressive parameter, Q is the seasonal moving average order,
S is the period length (in month in this work), and D denotes the number of differencing passes.

89 2.3 Implementation of ARIMA model

90 The procedure of estimating ARIMA model is given by the flowchart in Fig. 1 which involves91 the following steps:

92 (1) Stationary identification. The input time series for an ARIMA model needs to be stationary, 93 i.e., the time series should have a constant mean, variance, and autocorrelation through time. 94 Therefore, the stationarity of the data series needs to be identified first. If not, the non-stationary time 95 series is then required to be stationaried. Although the stationary test, such as unit root test and KPSS 96 test are used to identify if a time series is stationary, plotting approaches based on scatter diagram, 97 autocorrelation function diagram, and partial correlation function diagram are often used. The latter 98 approach can usually provide not only the information whether the testing time series is stationary but 99 indicate the order of the differencing which is needed to stationarize the time series. In this paper, we 100 identify the stationarity of a time series from the autocorrelation function diagram, and partial 101 correlation function diagram.

102 If a time series is identified nonstationary, differencing is usually made to stationarize the time 103 series. In the differencing method, the correct amount of differencing is normally the lowest order of 104 differencing that yields a time series which fluctuates around a well-defined mean value and whose 105 autocorrelation function (ACF) plot decays fairly rapidly to zero, either from above or below. The 106 time series is often transformed for stabilizing its variance through proper transformation, e.g., 107 logarithmic transformation. Although logarithmic transformation is commonly used to stabilize the 108 variance of a time series rather than directly stationarize a time series, the reduction in the variance of 109 a time series is usually helpful to reduce the order of difference in order to make it stationary.

110 (2) Identification of the order of ARIMA model. After a time series has been stationarized, 111 the next step is to determine the order terms of its ARIMA model, i.e., the order of differencing, dfor nonstational time series, the order of auto-regression, p, the order of moving average, q, and 112 113 the seasonal terms if the data series show seasonality. While one could just try some different 114 combinations of terms and see what works best strictly, the more systematic and common way is to tentatively identify the orders of the ARIMA model by looking at the autocorrelation function (ACF) 115 116 and partial autocorrelation (PACF) plots of the sationarized time series. The ACF plot is merely a bar 117 chart of the coefficients of correlation between a time series and lags of itself and the PACF plot present a plot of the partial correlation coefficients between the series and lags of itself. The detailed 118 119 guidelines for identifying ARIMA model parameters based on ACF and PACF, can be found 120 elsewhere, e.g., Pankratz (1983). It should be noted that, to be strict, the ARIMA model built in this 121 step is actually an ARMA model with if the time series is stationary, which is in fact a special case of ARIMA model with d = 0. 122

(3) Estimation of ARIMA model parameters. While least square methods (linear or nonlinear)
are often used for the parameter estimation, we use the maximum likelihood method (Mcleod, 1983;
Melard, 1984) in this paper. A *t*-test is also performed to test the statistical significance.

(4) White noise test for residual sequence. It is necessary to evaluate the established ARIMA model with estimated parameters before using it to make forecasting. We use white noise test here. If the residual sequence is not a white noise, some useful information has not been extracted and the 129 model needs to be further tuned. The method is illustrated as follows.

130 Null hypothesis:
$$H_0: \operatorname{corr}(e_t, e_{t-k}) = 0 \quad \forall k, t$$

131 Alternative hypothesis:
$$H_1 : \operatorname{corr}(e_{t_0}, e_{t_0-k_0}) \neq 0 \quad \exists k_0, t_0$$

132 The autocorrelation of the data series is measured by the autocorrelation coefficient which is133 defined as

134
$$r_{k} = \frac{\sum_{t=k+1}^{n} e_{t}e_{t-k}}{\sum_{t=1}^{n} e_{t}^{2}} \qquad (k = 1, 2, \cdots, m)$$
(7)

135 where *n* is the number of cases of sample of series for white noise test, *m* is the maximum number of 136 lag. In practice, *m* uses the value of $\left[\frac{n}{10}\right]$ when n is very large and $\left[\frac{n}{4}\right]$ when n is small. 137 When $n \to \infty$, $\sqrt{n}r_k \sim N(0,1)$.

138 The test statistics is given by

139
$$Q = n(n+2)\sum_{k=1}^{m} \frac{r_k^2}{n-k}$$
(8)

140 Given the degree of confidence of $1-\alpha$, if

141
$$Q < \chi_{\alpha}^{2}(m-p-q)$$
(9)

142 Then Q fits the χ^2 distribution at the significance of $1-\alpha$ and the null hypothesis is accepted.

143 (5) Hydrological forecasting. The linear least squares method is usually applied for 144 rainfall-runoff prediction. In general, based on the n observation values, the values of future L145 time steps can be estimated (Kohn et al. 1986).

146 **3. Improvement of conventional ARIMA model**

147 Seasonal ARIMA models apply for time series which arranges in order with a certain time

148 interval or step, e.g., a month. However, in this case, while the seasonal ARIMA model is capable of 149 dealing with the inter-annual variation of each monthly of a monthly data series, the information of 150 inter-monthly variation of the time series may be lost. For example, after an order of 12 of seasonal 151 differencing (term S in a general seasonal ARIMA model) of a monthly time series, the original 152 monthly series has been migrated to a new time series without seasonality. A nonseasonal ARIMA 153 model is then fitted to the new time series where the inter-monthly variation of original monthly time 154 series has also migrated to the inter-monthly variation of the new series after seasonal differencing. 155 The transformation of inter-monthly variation of original monthly data to the new inter-monthly 156 variation of seasonally differenced series may result in loss of accuracy of model performance. In this 157 study, twelve individual seasonal ARIMA models for precipitation prediction for each month are built 158 from each monthly data series, e.g., the January data series from 1951 to 2000, which are referred to 159 as ARIMA models of inter-annual variation ignoring the inter-monthly variation.

160 In order to prevent from losing the inter-monthly variation information, we propose in this study 161 the following improvement to the conventional seasonal ARIMA model, which simultaneously takes into account both kinds of temporal variation (inter-annual variation and inter-monthly variation). 162 163 Clustering analysis is first applied to classify the monthly data series and extract characteristics of 164 each data series class (Sun et al. 2005). In this study, we use Euclidean distance as the distance 165 measurement in clustering analysis. The characteristics of each data series refer to the maximum, 166 minimum, and truncated mean of the series of this class. A linear regression model is then built with 167 hydrological variable to be predicted, e.g., monthly precipitation, as dependent variables and with 168 maximum, minimum, and truncated mean of each class as independent variables in the linear 169 regression model. For example, a monthly precipitation would be described as a linear regression 170 function of the maximum, minimum, and truncated mean of the data series of a class where this 171 month's precipitation has been clustered in the clustering analysis. A conventional seasonal ARIMA 172 model is built for the maximum, minimum, and truncated mean of each class, respectively, accounting 173 for the inter-monthly variation of each characteristic variable. By this way, we are trying to avoid losing the inter-monthly variation information. The implementation of the improved ARIMA model 174 175 involves the following procedure, as illustrated in Fig. 2.

i). Perform clustering analysis on monthly data, and group the months with similarhydrological variation.

178 ii). Find the maximum, minimum, and truncated mean of each cluster.

179 iii). Build linear regression models and determine the associated parameters for each monthly
180 data series. For example, for the precipitation in the *i*-th month,

181
$$y_i = a_i y_{j,\max} + b_i y_{j,\min} + c_i y_{j,avg} + d_i$$
 (10)

182 where a_i , b_i , c_i , and d_i are the coefficients in the model for the *i*-th month 183 hydrologic parameter, e.g., precipitation, which need to be estimated, and $y_{j,max}$, $y_{j,min}$, 184 and $y_{j,avg}$ are respectively the maximum, minimum, and truncated mean of the *j*-th 185 class where the time series of the *i*-th month is identified in cluster analysis.

iv). Build ARIMA models for the maximum, minimum, and truncated mean of each class and
 predict the characteristics for the time year of interest using the established ARIMA models.

v). Substitute the predicted characteristics into the linear regression model built in Equation (10)
and obtain the monthly hydrologic variable, say precipitation.

190 **4. Case study**

191 In this section, we are presenting an application of the proposed improved ARIMA model to the 192 precipitation forecasting of Lanzhou precipitation station in Lanzhou, China. Lanzhou is located in the 193 upper basin of Yellow River. It has a continental climate of mid-temperate zone, with an average precipitation of 360 mm and mean temperature of 10°C. In general, rainfall seasons are May through 194 195 September, while drought occurs in spring and winter. The Lanzhou precipitation station is located at 196 103.70 E, 35.90 N. The monthly precipitation data from 1951 to 2000 is used for parameter 197 estimation and the monthly precipitations of 2001 are then predicted using the proposed model and 198 compared with the observation values. In order to show the improvement of this present approach, we 199 first build a conventional seasonal ARIMA model and a set of 12 ARIMA models for each monthly 200 precipitation series which account for the seasonal variation. The improved ARIMA model 201 accounting for both inter-month and inter-annual variation of monthly precipitation time series is then 202 built using the presented approach and its prediction results are compared with the conventional 203 ARIMA model and seasonal ARIMA model, as well as auto-regressive models.

204 4.1 Conventional seasonal ARMA modeling

205 The precipitation at the Lanzhou precipitation station from 1951 through 2001 and from 1991 206 through 2001 are plotted as shown Fig. 3 (a) and (b) respectively. The two figures show less 207 precipitation in winter and spring and more in summer and autumn. Fluctuation occurs to the data 208 during high precipitation seasons. Using power transformation with an order of 1/3, fluctuations at 209 high values are removed and the data become stationary, as shown in Fig. 3(c). According to 210 autocorrelation and partial correlation functions, as shown in Fig. 4, seasonal term with a period of 12 211 exists. With the difference elimination method, the order of the model can be determined from, and 212 the following seasonal ARIMA model is obtained.

213
$$(1-B^{12})y_t = (1-\theta_1 B)(1-\theta_2 B^{12})u_t$$
(11)

The maximum-likelihood method is then used for parameter estimation and the results are listed in Table 1. As shown in Table 1, parameter estimation is statistically significant. A white noise test is performed for the residual sequence. If the test does not pass, the model needs to be improved. As shown in Table 2, with a significance level of 5%, the test is passed, i.e., the useful information is extracted and the model is acceptable.

219 4.2 Individual ARIMA model for each month data series

As discussed in Section 2.2, the data can be classified into 12 groups associated with each month respectively. Stationary identification, stationary treatment, model identification, parameter estimation and residual test are performed for the 12 groups of data. A total of 12 ARIMA models are built and the estimated parameters are shown in Table 3.

4.3 The improved ARIMA model based on clustering and regression analysis

Box-Cox transformation is applied as a pretreatment of data for clustering analysis in order to stable the variance of the monthly precipitation data series. Given that the precipitation has values of zero resulting in negative infinity in the transformation, Box-Cox transformation (Thyer et al., 2002; Meloun et al., 2005; Ip et al., 2004) is corrected as follows.

229 Data after transformation =
$$\begin{cases} \frac{(\text{original data} + 1)^{\alpha} - 1}{\alpha} & \alpha \neq 0\\ \log(\text{original data}) & \alpha = 0 \end{cases}$$

After Box-Cox transformation, as shown in Fig. 6, the data are much more symmetric than the original data series, which is helpful for the later clustering analysis. Moreover, it can be seen that there are many zero precipitation values in the raw monthly precipitation data series and so does the transferred data. This indicates that the samples of data sequence may not be from one individual population but from multiple populations which further implies the necessarily of clustering analysis for the data series. Clustering analysis with Euclidean distance is then applied which indicates that the monthly precipitation sequences can be clustered into three classes, as shown in Fig. 7.

It is interesting that the clustering results are mostly coincides with the precipitation season. For example, Class 1 looks like corresponding to the drought season while Class 3 corresponds to the rainfall season. After the clustering analysis to the monthly precipitation time series, the characteristics of each class, i.e., maximum, minimum, and truncated mean, are identified, as shown in Fig. 8. Whereas fluctuations in the mean and minimum data series are relatively small, relatively larger variation are shown in the maximum data series.

Linear regression models for each monthly precipitation are fitted using the characteristics of each class where the monthly precipitation data series is located. The parameters corresponding to each linear regression model are presented in Table 4 which pass the t-test at the significance of 0.05 indicating that those linear models fit their data series well respectively. Following the steps described
in Section 2.3, nine ARIMA modes are built for each of the characteristic variables of each class. The
estimated parameters are shown in Table 5. Auto-regressive models with orders of 24 and 36, or AR
(24) and AR (36), are also fitted to the monthly precipitation time series for comparative study with
the improved ARIMA model and conventional ARIMA model.

252 **5. Results and discussion**

253 The monthly precipitations of 2001 are predicted using the improved ARIMA model as well as the conventional seasonal ARIMA model, the 12 seasonal ARIMA models for the precipitation of 254 255 each month, and AR(24) and AR(36) models, the prediction results shown in Table 6 and Fig. 9.The absolute error of each method is 9.41, 11.49, 11.78, 17.05, and 17.82 mm for the improved ARIMA 256 257 model, conventional ARIMA model, individual ARIMA for each month data series, AR(24), and AR(36), respectively, indicating that the improved ARIMA presented in this paper performs the best 258 259 with the smallest errors. Compared with the conventional ARIMA model, the improved ARIMA model increases the prediction accuracy by 24%. 260

The conventional ARIMA model predicts accurately for March, June, August, ad November but mismatches the other months' precipitation. It predicts more accurately for October precipitation than the improved ARIMA model. The 12 individual ARIMA models for each month data series performs similarly to the conventional ARIMA model. The overall performance of AR(24) model does not show difference from that of AR(36) model; neither models perform as good as the improved ARIMA model or the conventional ARIMA model. However, the AR models give a better prediction for September precipitation of 2001 than the other two models.

While the improved ARIMA model catches the correct trend overall and predicts the monthly precipitation in most months with high accuracy, it predicts highly accurately for the dry seasons, such as January, February, March, November, and December. However, it overestimates the precipitation of July and October and underestimates the September precipitation significantly. After a closer look at the data, we find that the mean precipitations of July and October are 63.8 and 23.48 mm over the period of 1951 through 2000, respectively, whereas the observation precipitations of

both months in 2001 are 39.5 and 5.2mm, respectively, much lower than the average precipitation of 274 the two month. Over the 51 years period of 1951 through 2001, the precipitations of July and October 275 in 2001 are 8th and 14th smallest, respectively. However, the precipitations of July and October in 276 2001 are the 2nd and 3rd smallest from 1991 to 2001, respectively and significantly smaller than the 277 precipitation of other months. This may be the reason that the improved and conventional model 278 279 underestimates for these two months. However, it is interesting that the AR models underestimates the 280 July precipitation but overestimates the October precipitation. This may be because of the much lower 281 precipitation in July, 2000 and much higher precipitation in October, 2000, relative to the July and 282 October in 2001, which, we believe, dominate the prediction of AR models. Similarly, the September precipitation of 2000 is close to the precipitation of September in 2001, which results a better AR 283 284 prediction in that month. According to the performance of AR models, we expect an improvement if we apply AR model to stationarized data series rather than the raw data series. 285

While the mean precipitation of September is 44.99 mm over the period of 1951 through 2000, the observation of September in 2001 is 82mm, the 4th largest one from 1951-2001, and the largest on in past 45 years. Furthermore, September, 2001 is the only one whose precipitation is larger than the August's precipitation in the previous ten years. These facts clearly show that the precipitation of September, 2001, is an extreme value, or outlier from statistical point of view. Therefore, it is fair to conclude that the built ARIMA model needs to be further improved for extreme situations.

292 Given that both the inter-annual variation and inter-monthly variation of the hydrological data 293 effect the prediction of hydrological time series, it is better to account for both for better prediction. 294 Inter-monthly data may result from different populations as well as nonstationary factors, so the 295 conventional seasonal ARIMA model which usually neglect the inter-monthly variations is not 296 effective enough. An improved ARIMA model has been built in this paper taking account for both 297 inter-annual and inter-monthly variation of hydrological data. Based on clustering analysis and 298 regression, much more information is extracted from the data series. A case study is conducted for the 299 precipitation of Lanzhou precipitation station with the improved ARIMA model and the comparison 300 with the conventional ARIMA model indicates that the accuracy of the improved ARIMA model is

301 significantly higher than that of the conventional ARIMA model. This improved approach can be 302 applicable to other hydrological processes prediction with time series data, such as runoff, water level, 303 and water temperature.

304 Apparently, the present model could be further improved, especially for the prediction of 305 extreme phenomena. Given that the selection of clustering method does affect model performance, 306 different clustering methods, e.g., the definition of distance in the hierarchical clustering can be 307 applied (Wang et al. 2005) to obtain better fittings. Characteristics value should be constructed by the 308 features of hydrological time series, not limited to the extreme or mean values. A higher order of 309 regression model rather than the linear regression may be used for the hydrologic forecasting. Last but 310 not the least, artificial intelligence approaches, such as neural network or support vector machine, can 311 be used to further improve the proposed ARIMA model.

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Table 1. Estimated parameters of the conventional seasonal ARMA model

Parameter	Estimated value	Standard deviation	t - test	Tail probability
$ heta_{ m l}$	-0.16379	0.03959	-4.14	<.0001
$ heta_2$	0.93434	0.02117	44.14	<.0001

Table 2. Autocorrelation of the residuals of the conventional seasonal ARIMA model

AR Order	χ^2 statistic	Degree of freedom	Tail probability	Autocorrelations of residue*					
6	0.770	4	0.943	0.000	-0.007	-0.018	0.021	-0.007	0.020
12	6.910	10	0.734	0.013	0.014	0.012	-0.043	0.086	-0.019
18	13.400	16	0.643	0.092	0.014	0.031	-0.004	0.021	0.020
24	16.810	22	0.774	0.042	0.007	-0.022	-0.026	-0.032	0.039
30	20.650	28	0.840	0.050	-0.031	-0.048	0.003	0.018	0.008
36	28.100	34	0.752	0.045	0.018	0.064	-0.044	0.036	0.044
42	30.900	40	0.849	0.057	-0.015	0.019	0.023	0.006	-0.001
48	52.940	46	0.224	-0.012	0.040	-0.022	0.032	-0.079	-0.156

*: Autocorrelations of residue for lag 1 through lag 48, 6 lags per row from Column 5 through 10.

Table 3. Seasonal ARIMA models for each month

Month	Model	ML parameter estimation
1	$(1 - \alpha B)y_t = (1 - \beta B)u_t$	$\alpha = -0.95, \ \beta = -0.97$
2	$(1-\alpha B^2)y_t = u_t$	$\alpha = -0.49$
3	$y_t = (1 - \beta B)u_t$	$\beta = 0.38$
4	$y_t = (1 - \beta_1 B - \beta_2 B^2) u_t$	$\beta_1 = 0.27, \ \beta_2 = -0.22$
5	$y_t = (1 - \beta B^2) u_t$	$\beta = -0.30$
6	$y_t = (1 - \beta B)u_t$	$\beta = -0.32$
7	$y_t = (1 - \beta B^2) u_t$	$\beta = -0.3349$
8	$(1 - \alpha B)y_t = (1 - \beta B)u_t$	$\alpha = -0.182, \ \beta = -0.0528$
9	$(1 - \alpha B)y_t = (1 - \beta B)u_t$	$\alpha = 0.956, \ \beta = 0.469$
10	$y_t = (1 - \beta B)u_t$	$\beta = -0.32$
11	$(1 - \alpha B)y_t = (1 - \beta B)u_t$	$\alpha = 0.681, \ \beta = 0.741$
12	$(1 - \alpha B)y_t = (1 - \beta B)u_t$	$\alpha = 0.650, \ \beta = 0.766$

 Table 4. Estimated parameters for linear regression models

Class	Month	d_i^*	a_i^*	c_i^*	b_i^*
	1	0.16	0.09	0.39	0.23
1	2	0.21	-0.12	1.21	-0.14
1	11	-0.54	0.30	1.51	-0.62
	12	0.16	-0.27	0.89	0.53
	3	1.92	-0.50	0.46	0.53
2	4	-0.39	-0.57	2.33	-0.62
	10	-1.53	1.07	0.21	0.09
	5	2.17	-0.41	0.22	0.98
	6	-0.19	-0.22	1.49	-0.35
3	7	-0.22	0.27	1.05	-0.35
	8	-2.11	1.07	0.24	0.05
	9	0.35	-0.72	2.01	-0.33

*: See Eq. (10) for definition.

Table 5. Parameters of ARIMA models for characteristic variables of each class

Class	Characteristic variable	ARIMA model	ML para estima		Standard estim		Value of P
	maximum	$(1-B)(1-\alpha B)y_t = u_t$	-0.5	6	0.	13	< 0.0001
1	mean	$(1-B)y_t = (1-\beta B)u_t$	0.92		0.07		< 0.0001
	minimum	$(1-B)^2 y_t = (1-\beta B)^2 u_t$	0.84		0.09		< 0.0001
	maximum	$(1-B)y_t = (1-\beta B)^2 u_t$	-0.3	0	0.	14	0.00311
2	mean	$(1-\alpha B^2)(1-B)^2 y_t = u_t$	-0.52		0.12		< 0.0001
	minimum	$(1-\alpha B^2)(1-B)^2 y_t = u_t$	-0.64		0.11		< 0.001
	maximum	$(1-\alpha B^2)(1-B)^2 y_t = u_t$	-0.4	5	0.	13	0.0006
3	mean	$(1 - \alpha B)^2 (1 - B)^2 y_t = (1 - \beta B^4) u_t$	-0.82	0.81	0.20	0.16	< 0.0001
	minimum	$(1 - \alpha B)^2 (1 - B)^2 y_t = (1 - \beta B^4) u_t$	-0.81	0.80	0.12	0.17	< 0.0001

Table 6. Predicted monthly precipitation data for 2001

Month (2001)	Observation (mm)			Predicti improved model	ARIMA	Predicti conventior model	nal ARMA	Predictic seasonal models	ARIMA	Prediction b model (, , ,	Prediction I model	
		prediction	residual	prediction	residual	prediction	residual	prediction	residual	prediction	residual		
1	2.8	2.54	-0.25	0	-2.8	1.14	-1.66	0.27	-2.53	0.57	-2.23		
2	1.9	1.897	-0.003	0	-1.9	3.58	1.68	6.4	4.5	6.4	4.5		
3	0	0.099	0.099	5.38	5.38	12.10	12.10	4.89	4.89	5.24	5.24		
4	22.2	12.32	-9.871	11.99	-10.21	12.32	-9.88	5.81	-16.3	7.25	-14.9		
5	11.1	12.61	1.515	31.26	20.16	33.17	22.07	6.49	-4.61	12.05	0.95		
6	33	33.58	0.582	41.28	8.28	38.16	5.16	77.86	44.86	79.75	46.75		
7	39.5	60.26	20.76	64.88	25.38	47.19	7.69	22.55	-16.9	20.09	-19.4		
8	69.8	72.92	3.12	71.82	2.02	84.12	14.32	110.5	40.72	114.5	44.73		
9	82	32.5	-49.5	37.98	-44.02	35.17	-46.83	65.89	-16.11	63.2	-18.8		
10	5.2	32.03	26.83	20.15	14.95	24.37	19.17	55.45	50.25	58.78	53.58		
11	1.9	1.532	-0.368	0	-1.9	2.68	0.78	3.9	2	3.79	1.89		
12	0.9	0.898	-0.002	0	-0.9	0.94	0.04	0	-0.9	0	-0.9		
	ibsolute error (mm)	9.4	1	11.4	19	11.7	78	17.0	15	17.8	32		





Fig. 2. Prediction steps of ARIMA model based on clustering and regressive analysis



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Fig. 4. Autocorrelation and Partial Correlation plots of data series Upper: Autocorrelation; Lower: Partial correlation



Fig. 5. Autocorrelation and Partial Correlation plots of data series after differencing

Upper: Autocorrelation; Lower: Partial correlation











Fig. 6. Monthly precipitation series before and after Box-Cox transformation



Fig. 7. Clusters of monthly precipitation time series





Fig. 8. Characteristics of each time series class. Upper: first class; Middle: second class; Lower: third class





Fig. 9. Comparison between predictions and observation