Nonlinear Processes in Geophysics (2005) 12: 373–379 SRef-ID: 1607-7946/npg/2005-12-373 European Geosciences Union © 2005 Author(s). This work is licensed under a Creative Commons License.



# Deeper understanding of non-linear geodetic data inversion using a quantitative sensitivity analysis

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**Abstract.** A quantitative global sensitivity analysis (SA) is applied to the non-linear inversion of gravity changes and displacement data which measured in an active volcanic area. The common inversion of this data is based on the solution of the generalized Navier equations which couples both types of observation, gravity and displacement, in a homogeneous half space. The sensitivity analysis has been carried out using Sobol's variance-based approach which produces the total sensitivity indices (TSI), so that all interactions between the unknown input parameters are taken into account. Results of the SA show quite different sensitivities for the measured changes as they relate to the unknown parameters for the east, north and height component, as well as the pressure, radial and mass component of an elastic-gravitational source. The TSIs are implemented into the inversion in order to stabilize the computation of the unknown parameters, which showed wide dispersion ranges in earlier optimization approaches. Samples which were computed using a genetic algorithm (GA) optimization are compared to samples in which the results of the global sensitivity analysis are integrated by a reweighting of the cofactor matrix in the objective function. The comparison shows that the implementation of the TSI's can decrease the dispersion rate of unknown input parameters, producing a great improvement the reliable determination of the unknown parameters.

#### 1 Introduction

Sensitivity analyses are used in a variety of research and engineering fields, where its application is widespread. The determination

 of the influence of a certain unknown input parameter to the output value qualitatively and also quantitatively

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- if, and which of, the parameters interact with each other
- which of the unknown input parameters should be determined more accurately in order to reduce the variance of the output values
- if there are parameters which are significant or can be eliminated from the model

are only some examples. Saltelli et al. (2000, 2004) give a complete overview of the different types of sensitivity analyses as well as how to implement them according to each particular purpose.

The application of SAs can be found in the modeling of various branches of volcanology, e.g. volcanic conduit flow modeling, Proussevitch and Sahagian (2004), magma and pressure source modeling, Tiampo et al. (2000), modeling of CO<sub>2</sub>, Schmid et al. (2003), landslide modeling, Tinti and Zaniboni (2004), and ash cloud modeling, Peterson and Dean (2003).

Most of the applied SA techniques have a local character. In local approaches the sensitivity of each unknown input value is computed by keeping the other parameter fixed and only varying the certain input parameter in a local area around its nominal value. These can be interpreted as one-at-a-time experiments (OAT). One drawback of OATtechniques is that it is not possible to compute the effects which are caused by the interactions between the unknown input parameters. Furthermore, OAT techniques tend to evaluate qualitative sensitivity results, Saltelli et al. (2004); they determine a ranking of the input parameters but do not quantify by how much one parameter is more important than another. Both a quantitative result as well as the computation of interactions between the unknown input parameters can be evaluated by global, quantitative methods such as those applied in this study using Sobol' method.

As a case study, gravity data and three-dimensional displacements were measured in an active volcanic area and inverted together in order to find the most reliable source for

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unknown input parameter	lower bound	upper bound
east (10 <sup>3</sup> m)	435	441
north (10 <sup>3</sup> m)	9160	9170
height $(10^3 \text{ m})$	0.01	3
pressure (10 <sup>5</sup> Pa)	-10	100
radial (10 <sup>3</sup> m)	0	2

-1

2

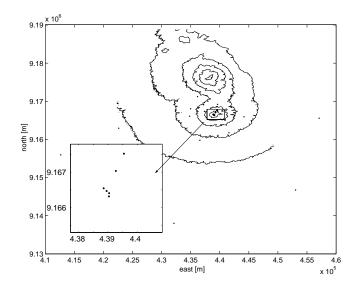
mass (10<sup>12</sup> kg)

**Table 1.** Range limitations of the unknown input parameters used for the SA computation.

the measured changes in time. By anticipating a subsurface body which produces a given change in density and pressure between two measurement epochs, we can model both the location as well as the gravity on the surface. The observed changes in gravity and the three-dimensional displacements measured over a certain time period can be interpreted as the influence of this change in the source properties. Such a source can be modeled in volcanic areas as a magma chamber but also as another body, which is filled by a certain material and includes a specified pressure. Other possible explanations of such sources are voids that are filled with fluids, or bodies in which the gas pressure is increasing that would suggest highly explosive, dangerous volcanic activity.

The unknown parameters of the source (given by the east, north and height component as well as the pressure, radial and mass component) were determined by a non-linear inversion which is based on the Navier-Stokes equations, coupling elastic and gravitational effects. The inversion has been optimized by a GA approach, which maximizes the objective function that is given as the  $1/\chi(comp.)^2$  value. This is computed by taking all types of observations into account, Eq. (12). Initial samples, Tiede et al. (2004)<sup>1</sup> show that the location as well as the mass can be determined with only a small dispersion rate. However, the determination of the radial and pressure component of the source show large variations which cover nearly the entire defined range of the unknown parameters. As a result, it follows that the determination of the pressure and radial parameter is poorly constrained, with high standard deviations of the mean values and signalling that these values could not be determined significantly.

Due to the fact that the sensitivity to the unknown parameters to the different types of is quite different, an investigation was made with the goal of stabilizing the inversion by the implementation of global SA results. The implementation is performed through a reweighting of the cofactor matrice  $Q_{ll}$  which is implied in the  $1/\chi$  (comp.)<sup>2</sup> value, Eq. (12). For that



**Fig. 1.** Distribution of those data locations used for the SA. Every observation point consists of gravity change as well as displacements in east, north and height direction.

purpose, the data set which was the basis of the work in Tiede et al.  $(2004)^1$  was used. The point distribution is given in Fig. 1. At each of the 20 observation points, gravity changes as well as displacements in the east, north and height component were determined. The topography is represented by the isolines. The limitation ranges of the unknown parameters for the quantitative SA are set according to initial results of the GA optimization (Tiede et al.,  $2004)^1$ . The ranges were set large enough so that the computed results did not reach the limits of the defined ranges. These boundaries are summarized in Table 1.

## 2 Underlying physical model

The multimodal objective function is based on the generalized Navier equations which couple elastic and gravitational effects in a homogeneous half space, given by Love (1911) and Rundle (1980)

$$0 = \nabla^{2} \boldsymbol{u} + \frac{1}{1 - 2\sigma} \nabla \nabla \cdot \boldsymbol{u} + \frac{\rho_{0} g}{\mu} \nabla (\boldsymbol{u} \cdot \boldsymbol{e}_{z})$$
$$-\frac{\rho_{0}}{\mu} \nabla \phi - \frac{\rho_{0} g}{\mu} \boldsymbol{e}_{z} \nabla \cdot \boldsymbol{u} + \boldsymbol{X}$$
(1)

 $\nabla^2 \phi = 4\pi \rho_0 G \nabla \cdot \boldsymbol{u} + Y \tag{2}$ 

with u=displacement,  $\phi$ =gravitational potential, X=body force,  $\rho_0$ =undisturbed density, G=gravitational constant,  $ge_z$ =surface gravitational acceleration,  $\sigma$ =Poisson ratio,  $\mu$ =shear modulus and Y=gravitational source. With X=0, Y=0, Eqs. (1) and (2) are solved by Rundle (1980, 1982) for a layered homogeneous half space.

<sup>&</sup>lt;sup>1</sup>Tiede, C., Tiampo, K., Fernández, J., and Gerstenecker, C.: Initial Inversion Results for Elastic Gravitational Modeling via Genetic Algorithms at Merapi Volcano, Indonesia, J. Volcanol. Geotherm. Res., submitted, 2004.

Rundle (1982) evaluates the equations that are satisfied by the displacement vector  $\boldsymbol{u}$  and perturbation potential  $\phi$  by obtaining a general solution at the height z=0:

$$\mathbf{u} = M \int_0^\infty [x_0^1(0)\mathbf{P_0} + y_0^1(0)\mathbf{B_0}]kdk$$
 (3)

$$\phi = M \int_0^\infty \omega_0^1(0) J_0(kr) k dk \tag{4}$$

$$\delta g = -\frac{d\phi}{dz} = -M \int_0^\infty q_0^1(0) J_0(kr) k dk + 4\pi \rho_0 G u_z$$
 (5)

with M=mass of the intrusion,  $x_0^1(0)$ ,  $y_0^1(0)$ ,  $\omega_0^1(0)$ ,  $q_0^1(0)$  kernel functions, whose calculation is described in Rundle (1980), depend on the Fourier wave number k and are given as a function of the characteristics of the medium's layers Fernández and Rundle (1994).  $P_0$ ,  $B_0$ =vectors given in terms of Bessel function  $J_0(kr)$  of the first kind of order zero and  $\rho_0$  = density of the layer.

For the purposes of this inversion Poisson's ratio  $\sigma$  was chosen as 0.25 for an elastic medium and the Young's modulus E was anticipated to be 30 GPa, according to Beauducel et al. (2000). The mean density for this area is given as 2242 kg/m³, a value which was derived by preliminary gravity inversions in the area of interest.

### 3 Variance-based Sobol' SA

Due to the non-linear property of the given inversion problem, a global sensitivity analysis with the aim of apportioning the uncertainty in the output data due to the unknown input parameters was applied, Saltelli et al. (2000). Global SAs are based on the variation of all unknown input parameters at the same time, the computation over the full definition range of each unknown input parameter, and a form of probability density function (pdf) of each. In contrast, local SAs fix all unknowns and only vary one input parameter in a small range around the nominal value per time. A general global sensitivity concept, the variance-based SA is sampling-based, and therefore a Monte Carlo simulation is applied. In this work we applied Sobol' as well as the Fourier amplitude SA, FAST, also belonging to this same kind of global SAs. The main advantage of these methods is that the analytic structure of the model to be analyzed does not need to be known specifically. Schwieger (2004).

The main idea of these types of sensitivity analyses is based on the idea that one can determine the nature of the sensitivity through the variance V and then evaluate how the input variance contributes to the output variance. By setting  $(X_1, ..., X_k)$  as the vector of independent unknown input parameters and  $Y = f(X_1, ..., X_k)$  as the output value, with f as model function, an indicator for the importance of an input  $X_i$  can be set by evaluating the variance of the output  $Y(Y|X_i)$ . This is done by fixing  $X_i$  to its true value  $X_i$ .  $Y(Y|X_i)$  is called the conditional variance of Y with  $X_i = x_i$ . The true value of  $X_i$  is not known, so instead of

 $V(Y|X_i)$  the expectation of the conditional variance, noted as  $E[V(Y|X_i)]$  is studied, whereby it is built into all possible values of  $x_i$ . The variance of Y is given by

$$V(Y) = V(E[Y|X_i]) + E[V(Y|X_i)].$$
(6)

The first addend is called the variance of the conditional expectation and describes the importance of  $X_i$  on the variance Y, which is equivalent to the sensitivity of Y to  $X_i$ . Normalizing the sensitivity value  $S_i$  as the ratio between the variance of the expectation value and the variance of the output value leads to

$$S_i = \frac{V(E[Y|X_i])}{V(Y)} \tag{7}$$

and is called the first order sensitivity index, correlation ratio or importance measure and describes the main effect of the unknown parameter  $X_i$  on the output value Y. For an additive model the summation over the ratios of the unknown parameters results in 1, if interactions between the unknown input parameters exist, the entire decomposition of the objective function must be evaluated.

By propagating the variances of the unknown input parameters through the model, which determines the influence of this unknown parameter on the model output variance, some of the variance-based techniques can deliver quantitative as well as model independent sensitivity results.

The variance-based Sobol' sensitivity method explores the multidimensional space of the unknown input parameters X with a certain number of Monte Carlo samples. The sensitivity indices, both first order and also the higher interactions between the unknown input parameters, related to Sobol' (1993), are generated by a decomposition of the model function f in a k-dimensional factor space  $\Omega^k$  into summands of increasing dimensionality,

$$f(X_1, ..., X_k) = f_0 + \sum_{i=1}^k f_i(X_i) + \sum_{1 \le i < j \le k} f_{ij}(X_i, X_j) + ... + f_{1, ..., k}(X_1, ..., X_k)$$
(8)

with  $X_1, ..., X_k$ =unknown input parameters and  $f_0$ =const. In all functions of the decomposition the integrals over any of its own variables are zero and they are orthogonal. All terms in  $f(X_1, ..., X_k)$  can be evaluated by multidimensional integrals.

Squaring and integrating Eq. (8) over  $\Omega^k$  leads to the decomposition of the variance  $V(X_1, ..., X_k)$  of the output value  $f(X_1, ..., X_k)$ :

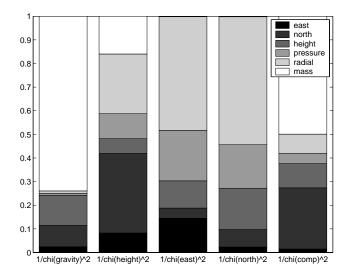
$$V(Y) = \sum_{i=1}^{k} V_i + \sum_{1 \le i \le k} V_{ij} + \dots + V_{1,\dots,k}$$
 (9)

with

$$V_{i} = V(E[Y|X_{i}])$$

$$V_{ij} = V(E[Y|X_{i}, X_{j}] - E[Y|X_{i}] - E[Y|X_{j}])$$
(10)

With the assumption that the unknown input values X are



**Fig. 2.** Normalized Sobol' first order indices for the five defined output parameters.

not correlated, the results can be obtained by

$$V_{ij} = V(E[Y|X_i, X_j]) - V_i - V_j$$
(11)

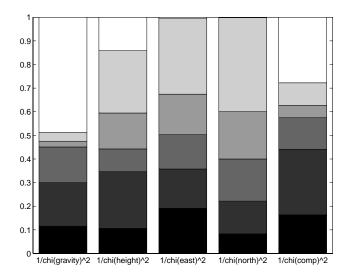
The first order sensitivity indices are given by  $S_i = V_i / V(Y)$ , higher order indices by  $S_{i_1,...,i_s} = V_{i_1,...,i_s} / V(Y)$ .

First order sensitivity indices  $S_i$  measure the main effect of each unknown parameter  $X_i$  on the output and are quantitative sensitivity results for additive models. The higher order indices  $S_{(i_1,...,i_s)}$  describe the interaction effects between the unknown input parameters  $X_{i_1},...,X_{i_s}$  on the output value. These effects are not included in the individual effects of  $X_{i_1},...,X_{i_s}$ .

The TSI of an unknown input parameter  $X_i$  is defined as the sum of all sensitivity indices, its main order effect as well as all the higher order effects in which this value appears. According to Saltelli et al. (2000) TSIs provide quantitative sensitivity analysis results for all kind of models independent of their model characteristics.

The SA, which is of an estimating nature, due to the lack of knowledge about the relation between input and output data as well as about the interactions between the unknown parameters, has been computed by the program Simlab, version 2.2, Saltelli et al. (2004). The general procedure to carry out the SA include the definition of the pdfs for the unknown input parameters, the generation of Monte Carlo samples for the unknown input parameters as well as the computation of the results of the physical underlying model using these samples, the analysis of the output variance, and a sensitivity analysis of the output variance in relation to the variation of the unknown input parameters, Schwieger (2004).

The unknown parameters east, north and height as well as pressure, radial and mass of the point source has been taken as input parameters for the quantitative, variance-based, global Sobol' SA. The output is characterized by the  $1/\chi()^2$  values, Eq. (12), including those for (gravity), (height), (east), (north) as well as (comp.) which is computed



**Fig. 3.** Normalized Sobol' Total Sensitivity Indices (TSI) for the five defined output parameters.

by taking all types of observations into account. Figure 1 shows an overview of the location configuration whereby at each of the 20 observation points, gravity changes, height, east and north displacements were measured. The  $\chi()^2$  values are computed by

$$\chi()^2 = \frac{v^T \mathbf{Q_{II}}^{-1} \mathbf{v}}{n - u} \tag{12}$$

with v as residuals between modeled and observed output values, specified by the type of observation (),  $\mathbf{Q_{ll}}$  through a cofactor matrix. The given variances of each observation of () lie on its diagonal, anticipating uncorrelated data, with n-u degrees of freedom (n as number of observations, u as number of unknown parameters).

The pdf of the unknown values were assumed uniform due to the fact that it is not possible to specify any area or certain value ranges which are more likely than others within the given described bounds. The SA consists of 28 672 Monte Carlo samples. Figure 2 and Fig. 3, show the normalized Sobol' first order indices and TSIs for the unknown input parameters. The bar plots are given for each of the five defined output values  $1/\chi$  ()<sup>2</sup> separately.

By comparing the first order indices with the TSI's, the results show clearly that only taking the first order indices into account would lead to large mistakes in the anticipation of the influence of a certain unknown to the different kind of data. By computing the percentage of the first order effect compared to the corresponding TSI, only the sensitivity concerning the mass component for the output values  $1/\chi$  (gravity)<sup>2</sup> and  $1/\chi$  (north)<sup>2</sup> are influenced primarily by the first order indices. All other TSIs are driven primarily by interactions between the input parameters.

By analyzing the Sobol' TSI's, the influences on the observed values due to the unknown input parameters are obvious:

Table 2. Range limitations of	the unknown	input parameters used
in the GA.		

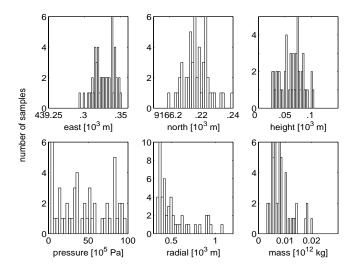
unknown input parammeter	lower bound	upper bound
east (10 <sup>3</sup> m)	439.2	439.5
north $(10^3 \text{ m})$	9166.12	9166.24
height (10 <sup>3</sup> m)	0.01	0.2
pressure (10 <sup>5</sup> Pa)	-10	100
radial (10 <sup>3</sup> m)	0	1.5
mass (10 <sup>12</sup> kg)	0	0.08

- $-1/\chi$  (gravity)<sup>2</sup> values are influenced in large part by the mass of the source. The three location parameters of the source have similar influences on this output value.  $1/\chi$  (gravity)<sup>2</sup> values are only few sensitive to changes in the pressure and radius of the unknown source.
- $1/\chi$  (height)<sup>2</sup> values are, surprisingly, equally sensitive to the radial component as well to the north component of the source.
- $-1/\chi (east)^2$  values are sensitive to changes in the radial component of the source and almost equally sensitive to changes in all other input parameters except the mass. The mass does not influence the output value at all.
- $1/\chi$  (north)<sup>2</sup> values are most sensitive to changes in the radial component of the source. The mass has little to no influence and the east component has only a small influence. The other TSI's are approximately the same size.
- $1/\chi$  (comp.)<sup>2</sup> values are most sensitive to changes in the mass component as well as the north component.

This summary of the different sensitivities concerning the unknown input parameters points out the great need of a joint inversion of both displacements and gravity changes.

## 4 Implementation of TSIs into GA

As mentioned in the introduction, initial results of a GA approach, Tiede et al.  $(2004)^1$  showed that the unknown parameters pressure and radius of the source could not be determined significantly without any additional information. The TSIs (caused by the unknown parameters) of the different  $1/\chi()^2$  values show that the sensibility of the observed displacements to changes in the radial component are much larger than the one of the gravity changes. Therefore, the TSI values governing the radial component TSI(r) of the unknown source has been taken as a reweighting factor in the cofactor matrix  $\mathbf{Q}_{\mathbf{II}(\mathbf{r})}$  of the objective function  $1/\chi(\text{comp.})^2$ , which is computed by taking all kind of measurements into



**Fig. 4.** Histograms for the unknown parameters computed by 50 GA samples without reweighting  $Q_{II}$ .

account. The reweighted cofactor matrice  $Q_{ll(r)}$  is given by

$$\mathbf{Q_{ll(r)}} = diag \left( \sigma_{g_i} \cdot \left( \frac{TSI(r)}{TSI(r)_g} \right)^2, \sigma_{H_i} \cdot \left( \frac{TSI(r)}{TSI(r)_H} \right)^2, \\ \sigma_{E_i} \cdot \left( \frac{TSI(r)}{TSI(r)_E} \right)^2, \sigma_{N_i} \cdot \left( \frac{TSI(r)}{TSI(r)_N} \right)^2 \right)$$
(13)
$$TSI(r) = TSI(r)_g + TSI(r)_H + TSI(r)_E + TSI(r)_N$$

with i=1...20,  $\sigma_g$ ,  $\sigma_H$ ,  $\sigma_E$  and  $\sigma_N$ =variance of gravity change, change in height, east and north component of the i-th observation point.

Fifty samples of a GA approach, explained in detail in Tiampo et al. (2000), have been computed with the implemented reweighted  $Q_{ll(r)}$  matrix and are compared to the original samples which were carried out without any reweighting. The population size is given by 100. 1000 is chosen as the maximum number of generations, the limitation bounds for the unknown parameters are set equal, Table 2

The results of the computation are shown in Fig. 4 for the GA optimization without reweighting and in Fig. 5 for the GA optimization with reweighting  $\mathbf{Q}_{\mathbf{ll}(\mathbf{r})}$  of the TSIs for the radial component of the unknown source. Table 3 lists the ranges of the unknown parameters for these two different computations. It can be seen that all ranges were decreased by the reweighted  $\mathbf{Q}_{\mathbf{ll}(\mathbf{r})}$ .

Comparing the  $\chi$  (comp.)<sup>2</sup> values of the best two models shows that the model with the reweighted  $Q_{ll(r)}$  matrix leads to  $\chi$  (comp.)<sup>2</sup>=115.847, whereby the best model determined by the normal GA leads to  $\chi$  (comp.)<sup>2</sup>=115.642. The small change for the worse of the reweighted result is explained by examination of the standard deviations of the output values whose weights are now changed according to the  $\mathbf{Q}_{\mathbf{ll(r)}}$  matrix.

unknown parameter	range without reweighting $Q_{ll}$	range with reweighting $Q_{ll(r)}$
east (10 <sup>3</sup> m)	0.059	0.048
north $(10^3 \text{ m})$	0.041	0.019
height (10 <sup>3</sup> m)	0.079	0.077
pressure (10 <sup>5</sup> Pa)	94.548	89.402
radial (10 <sup>3</sup> m)	0.752	0.462
mass (10 <sup>12</sup> kg)	0.017208	0.010536

**Table 3.** Ranges of unknown parameters determined by 50 sample of GA without and with reweighting  $Q_{ll(r)}$ .

## 5 Conclusions

The paper reviews the application of Sobol' variance-based SA, a quantitative global method for the determination of the TSI's of the unknown input parameters for each kind of observed output value.

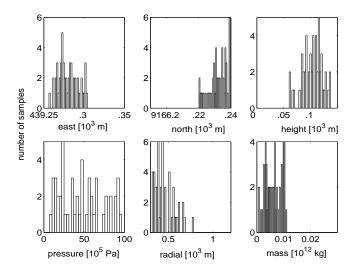
The application of the Sobol' sensitivity analysis shows different sensitivities for the different  $1/\chi()^2$  output values. In particular, the sensitivity concerning the mass, radial and pressure components for the  $1/\chi(\text{gravity})^2$  compared to the sensitivity against those values of the  $1/\chi(\text{height})^2$ ,  $1/\chi(\text{east})^2$  and  $1/\chi(\text{north})^2$  are very different. These different sensitivities demonstrate that there is a great need to invert gravity changes and displacement data in a common approach for the determination of an elastic-gravitational source.

Furthermore, if the different types of observation data show different sensitivities against the unknown input parameters, this information can be used to determine special unknown input parameters in more detail. By enlarging the weights of those observations which are most sensitive against differences of a certain unknown input parameter, this special unknown can be determined more accurately.

In this example, the reweighting approach results in a more homogeneous optimization. The sum of all residuals concerning gravity and displacement observations constructs the objective function to be minimized. By introducing the reweighting approach, the influence of the dominant sensitivity relating to the mass component of the gravity observations has been reduced, and the influence of the sensitivity concerning the radial component could be increased by the increase in the weights of the displacements.

The results of this approach show that it is possible to enlarge the accuracy of the determined radial component by the implementation of the reweighting factors. Although the fitness of the best chosen model is decreasing by a small amount, the benefits of the implementation are obvious.

The introduced implementation of the sensitivity analysis into an optimization might be applied in a many areas of interest. If the objective function is computed by the sum of different types of residuals (in this approach observed gravity changes, height, east and north displacements) and these



**Fig. 5.** Histograms for the unknown parameters computed by 50 GA samples with reweighting  $Q_{II(r)}$  by the TSIs.

observations have different sensitivities to the unknown input parameters, the information of the TSIs can be used to stabilize the optimization results. In that case, the reweighting according to the TSIs must be incorporated into the cofactor matrix  $Q_{ll(r)}$  in order to change the weights of the various types of output values according to their sensitivity.

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